CHANGE NOTICE			
Affected Document:	IRN/SCN Number	Date:	
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Authority:	Proposed Change Notice	Date:	
RFC-00413	PCN-IS-705G_RFC413	09-JUN-2020	

CLASSIFIED BY: N/A DECLASSIFY ON: N/A

Document Title: NAVSTAR GPS Space Segment/User Segment L5 Interfaces

RFC Title: Integrity Support Messages

Reason For Change (Driver):

- 1. Navigation integrity for Global Navigation Satellite Systems (GNSS) including GPS has, to date, been codified in performance standard(s) documentation. The implication is that receiver manufacturers must extract information manually and encode it into GNSS receivers. This has two negative effects: 1) operational receivers cannot be modified without a maintenance cycle when updated standards are released; 2) for other-than-GPS systems, receiver manufacturer reliance on documentation produced by foreign entities.
- 2. Affected documents:IS-GPS-200, IS-GPS-705, and IS-GPS-800

Description of Change:

Define an Integrity Support Message (ISM) that contains pertinent integrity information about GNSS constellations including, and that are compatible with, GPS and broadcast the ISM via CNAV (L2C & L5) and CNAV-2 (L1C). These messages enable the end user to perform Advanced Receiver Autonomous Integrity Monitoring (ARAIM).

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AUTHORIZED SIGNATURES	REPRESENTING	DATE
	GPS Enterprise	
	Space & Missile Systems Center (SMC) – LAAFB	

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Interface Control Contractor: SAIC (GPS SE&I) 200 N. Pacific Coast Highway, Suite 1800 El Segundo, CA 90245

CODE IDENT 66RP1

IS705-1496:

Section Number:

6.1.0-1

WAS:

AFMC	-	Air Force Materiel Command
AFSPC	-	Air Force Space Command
ASCII	-	American Standard Code for Information Interchange
bps	-	bits per second
BPSK	-	Bi-Phase Shift Key
C/A	-	Course/Acquisition
CDC	-	Clock Differential Correction
CEI	-	Clock, Ephemeris, Integrity
CNAV	-	Civil Navigation
CRC	-	Cyclic Redundancy Check
CS	-	Control Segment
dB	-	Decibel
dBc	-	Power ratio of a signal to a (unmodulated) carrier signal, expressed in decibels
dBi	-	Decibels with respect to isotropic antenna
dBW	-	Decibels with respect to 1 Watt
DC	-	Differential Correction
DoD	-	Department of Defense
ECEF	-	Earth-Centered, Earth-Fixed
ECI	-	Earth Centered Inertial
EDC	-	Ephemeris Differential Correction
EOL	-	End of Life
FEC	-	Forward Error Correction
GGTO	-	GPS/GNSS Time Offset
GNSS	-	Global Navigation Satellite System

GPS	-	Global Positioning System
GPSW	-	Global Positioning System Wing
Hz	-	Hertz
I5	-	In-phase Code on L5 Signal
ICC	-	Interface Control Contractor
ID	-	Identification
IODC	-	Issue of Data, Clock
IS	-	Interface Specification
ISC	-	Inter-Signal Correction
LNAV	-	Legacy Navigation
LSB	-	Least Significant Bit
MSB	-	Most Significant Bit
NAV	-	Navigation
NSI5	-	Non-Standard I-Code
NSQ5	-	Non-Standard Q-Code
OCS	-	Operational Control System
PIRN	-	Proposed Interface Revision Notice
PRN	-	Pseudo-Random Noise
P(Y)	-	Precise (Anti-Spoof) Code
Q5	-	Quadraphase code on L5 Signal
RF	-	Radio Frequency
RHCP	-	Right Hand Circular Polarization
RMS	-	Root Mean Square
SBAS	-	Satellite Based Augmentation System
sps	-	Symbols per Second.
SIS	-	Signal In Space
SS	-	Space Segment
SSV	-	Space Service Volume
SV	-	Space Vehicle

TBD	-	To Be Determined
TBS	-	To Be Supplied
TOW	-	Time Of Week
URA	-	User Range Accuracy
US	-	User Segment
USNO	-	US Naval Observatory
UTC	-	Coordinated Universal Time
WGS 84	-	World Geodetic System 1984
WN	-	Data Sequence Propagation Week Number
WN _e	-	Extended Week Number

Redlines :

AFMC	-	Air Force Materiel Command
AFSPC	-	Air Force Space Command
ARAIM	=	Advanced Receiver Autonomous Integrity Monitoring
ASCII	-	American Standard Code for Information Interchange
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C/A	-	Course/Acquisition
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dBi	-	Decibels with respect to isotropic antenna
dBW	-	Decibels with respect to 1 Watt
DC	-	Differential Correction
DoD	-	Department of Defense
ECEF	-	Earth-Centered, Earth-Fixed
ECI	-	Earth Centered Inertial
EDC	-	Ephemeris Differential Correction
EOL	-	End of Life
FEC	-	Forward Error Correction
GGTO	-	GPS/GNSS Time Offset
GNSS	-	Global Navigation Satellite System
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I5	-	In-phase Code on L5 Signal
ICC	-	Interface Control Contractor
ID	-	Identification
IODC	-	Issue of Data, Clock
IS	-	Interface Specification
ISC	-	Inter-Signal Correction
ISM	=	Integrity Support Message
LNAV	-	Legacy Navigation
LSB	-	Least Significant Bit
MSB	-	Most Significant Bit
MSO	=	Military Standing Order
NAV	-	Navigation
NSI5	-	Non-Standard I-Code
NSQ5	-	Non-Standard Q-Code
OCS	-	Operational Control System
PIRN	-	Proposed Interface Revision Notice
PRN	-	Pseudo-Random Noise
P(Y)	-	Precise (Anti-Spoof) Code
Q5	-	Quadraphase code on L5 Signal
RAIM	=	Receiver Autonomous Integrity Monitoring
RF	-	Radio Frequency
RHCP	-	Right Hand Circular Polarization
RMS	-	Root Mean Square
SBAS	-	Satellite Based Augmentation System
sps	-	Symbols per Second.
SIS	-	Signal In Space
SS	-	Space Segment
SSV	-	Space Service Volume

SV	-	Space Vehicle
TBD	-	To Be Determined
TBS	-	To Be Supplied
TOW	-	Time Of Week
TSO	=	Technical Standing Order
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US	-	User Segment
USNO	-	US Naval Observatory
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GGTO	-	GPS/GNSS Time Offset
GNSS	-	Global Navigation Satellite System
GPS	-	Global Positioning System
GPSW	-	Global Positioning System Wing

In-phase Code on L5 Signal	
ID	
IODC Issue of Data, Clock IS Interface Specification ISC Inter-Signal Correction ISM Integrity Support Message LNAV Legacy Navigation LSB Least Significant Bit MSB MSS Most Significant Bit MSO Military Standing Order NAV Navigation NSI5 Non-Standard I-Code NSQ5 Non-Standard I-Code OCS Operational Control System PIRN Proposed Interface Revision Notice PRN Precise (Anti-Spoof) Code Q5 Quadraphase code on L5 Signal RAIM Receiver Autonomous Integrity Monitoring RF Radio Frequency RHCP Right Hand Circular Polarization RMS Root Mean Square	
IS - Interface Specification ISC - Inter-Signal Correction ISM - Integrity Support Message LNAV - Legacy Navigation LSB - Least Significant Bit MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSIS - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code QS - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
ISC - Inter-Signal Correction ISM - Integrity Support Message LNAV - Legacy Navigation LSB - Least Significant Bit MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
ISM - Integrity Support Message LNAV - Legacy Navigation LSB - Least Significant Bit MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
LNAV - Legacy Navigation LSB - Least Significant Bit MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
LSB - Least Significant Bit MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
MSB - Most Significant Bit MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
MSO - Military Standing Order NAV - Navigation NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
NAV - Navigation NSIS - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
NSI5 - Non-Standard I-Code NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
NSQ5 - Non-Standard Q-Code OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
OCS - Operational Control System PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
PIRN - Proposed Interface Revision Notice PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
PRN - Pseudo-Random Noise P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
P(Y) - Precise (Anti-Spoof) Code Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
Q5 - Quadraphase code on L5 Signal RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
RAIM - Receiver Autonomous Integrity Monitoring RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
RF - Radio Frequency RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
RHCP - Right Hand Circular Polarization RMS - Root Mean Square	
RMS - Root Mean Square	
CDAC Catallita Danad Assessmentation Catallita	
SBAS - Satellite Based Augmentation System	
sps - Symbols per Second.	
SIS - Signal In Space	
SS - Space Segment	
SSV - Space Service Volume	

SV	-	Space Vehicle
TBD	-	To Be Determined
TBS	-	To Be Supplied
TOW	-	Time Of Week
TSO	-	Technical Standing Order
URA	-	User Range Accuracy
US	-	User Segment
USNO	-	US Naval Observatory
UTC	-	Coordinated Universal Time
WGS 84	-	World Geodetic System 1984
WN	-	Data Sequence Propagation Week Number
WN _e	-	Extended Week Number

Adding RAIM, ARAIM, MSO, TSO, and ISM to the abbreviation list.

Section Number:

20.3.2.0-1

WAS:

As shown in Figures 20-1 through 20-14, the L5 CNAV message structure utilizes a basic format of six-second 300-bit long messages. Each message contains a Cyclic Redundancy Check (CRC) parity block consisting of 24 bits covering the entire six-second message (300 bits) (reference Section 20.3.5).

Redlines:

As shown in Figures 20-1 through 20-1414a, the L5 CNAV message structure utilizes a basic format of six-second 300-bit long messages. Each message contains a Cyclic Redundancy Check (CRC) parity block consisting of 24 bits covering the entire six-second message (300 bits) (reference Section 20.3.5).

IS:

As shown in Figures 20-1 through 20-14a, the L5 CNAV message structure utilizes a basic format of six-second 300-bit long messages. Each message contains a Cyclic Redundancy Check (CRC) parity block consisting of 24 bits covering the entire six-second message (300 bits) (reference Section 20.3.5).

Rationale:

The new figure for the ISM will be Figure 20-14a to maintain numbering scheme. Making a global change to incorporate the new figure

IS705-1606:

Insertion after object IS705-1565(placed after text)

Figure 20-14. Message Type 15 - Text

Section Number:

20.3.3.0-30

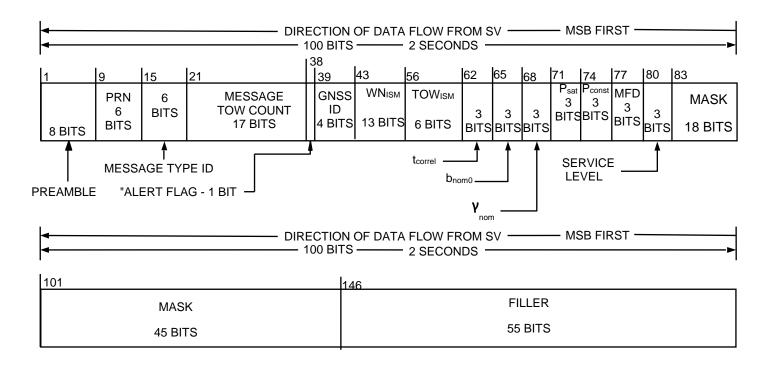
WAS:

<INSERTED OBJECT>

Redlines:

<INSERTED OBJECT>

IS:



DIRECTION OF DATA FLOW FROM SV — MSB FIRST — 100 BITS — 2 SECONDS — MSB FIRST — 100 BITS — 2 SECONDS — MSB FIRST — 100 BITS — 100 BI		
201	245	277
FILLER	ISM CRC	CRC
44 BITS	32 BITS	24 BITS

^{*} MESSAGE TOW COUNT = 17 MSBs OF ACTUAL TOW COUNT AT START OF NEXT 6-SECOND MESSAGE

Object Type : Figure
Rationale : Adding L5 message structure figure.
IS705-1608: Insertion after object IS705-1606
Section Number : 20.3.3.0-31
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Figure 20-14a. Message Type 40 – Integrity Support Message (ISM)
Rationale: Figure caption
IS705-1609 : Insertion after object IS705-365 (Sec 20.3.3.9)
20.3.3.9 Message Types 36 and 15 Text Messages.
Text messages are provided either in message type 36, Figure 20-9, or type 15, Figure 20-14. The specific contents of text message will be at the discretion of the Operating Command. Message type 36 can accommodate the transmission of 18 eight-bit ASCII characters. Message type 15 can accommodate the transmission of 29 eight-bit ASCII characters. The requisite bits shall occupy bits 39 through 274 of message type 15 and bits 128 through 275 of message type 36. The eight-bit ASCII characters shall be limited to the set described in paragraph 20.3.3.5.1.8 of IS-GPS-200.
Section Number: 20.3.3.10
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: Message Type 40 Integrity Support Message (ISM)
Rationale : New section for ARAIM users that has details on the ISM

IS705-1611: Insertion below object IS705-1609
Section Number : 20.3.3.10.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Figure 20-14a contains the structure of Message Type 40, Integrity Support Message (ISM). The contents of Message Type 40 are defined below, followed by material pertinent to the use of the ISM data. Users who implement Advanced Receiver Autonomous Integrity Monitoring (ARAIM) may use these parameters for the ARAIM algorithm as referenced in future TSO and MSO.
Rationale: Main ARAIM algorithms are found in the referenced documents. They are currently in work and when finalized the references need to be updated. Also spelling out ARAIM since it is the first mention of it.
IS705-1612: Insertion after object IS705-1611
Section Number : 20.3.3.10.1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>

IS:

Rationale:

Parameter Section

 ${\it Object\ Heading: ISM\ Parameter\ Content}$

IS705-1613: Insertion below object IS705-1612
Section Number: 20.3.3.10.1.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Message Type 40 shall contain the parameters related to GNSS constellation and satellite integrity parameters used for ARAIM algorithms.
Rationale: the message only has ISM parameters.
IS705-1614: Insertion after object IS705-1613
Section Number: 20.3.3.10.1.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : The bit lengths, scale factors, ranges, and units of these parameters are given in Table 20-XIa.
Rationale: Statement directing the user to the parameter table.

IS705-1615 :
Insertion after object IS705-1614
Section Number :
20.3.3.10.1.0-3
WAS:
<inserted object=""></inserted>
Redlines :
<inserted object=""></inserted>
IS:
The CS shall upload the current ISM parameters, when necessary, to the SVs.
Rationale :
Add requirement that makes it explicit that CS will upload this new message
IS705-1658 : Insertion after object IS705-1615
Section Number :
20.3.3.10.1.0-6
WAS:
<inserted object=""></inserted>
Redlines :
<inserted object=""></inserted>
IS:
Table 20-XIa – ISM Parameters
Rationale :
Parameter Table Caption

IS705-1618:

Insertion after object IS705-1658

Section Number:

20.3.3.10.1.0-7

WAS:

<INSERTED OBJECT>

Redlines:

<INSERTED OBJECT>

IS:

Parameter	No. of Bits**	Scale Factor (LSB)	Valid Range***	Units
GNSS ID	4			
$\mathrm{WN}_{\mathrm{ISM}}$	13	1		week
$\mathrm{TOW}_{\mathrm{ISM}}$	6	4	0 to 164	hours
t_{correl}	3		0 to 12	hours
$b_{\mathrm{nom}0}$	3		0 to 2	meter
$\gamma_{ m nom}$	3		0 to 2	
$\mathbf{P}_{\mathrm{sat}}$	3		1e ⁻³ to 1e ⁻⁹	
P_{const}	3		1e ⁻³ to 1e ⁻⁹	
MFD	3		0.25 to 24	hours
Service Level*	3			
Mask***	63			

^{*} See Table 20-XIb for Service Level Descriptions

Object Type: Table

Rationale:

Adding Parameter table for the ISMs

^{**} See Figure 20-14a for complete bit allocation in Message Type 40 $\,$

^{***} Unless otherwise indicated in this column, valid range is the maximum range attainable with indicated bit allocation and scale factor

^{****} See Table 20-XIc for Mask bit mapping

IS705-1619: Insertion after object IS705-1618
Section Number : 20.3.3.10.1.1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: GNSS Constellation ID
Rationale: First ISM parameter in the Message Structure. Sections will go in order of the message structure
IS705-1620 : Insertion below object IS705-1619
Insertion below object IS705-1619 Section Number:
Insertion below object IS705-1619 Section Number: 20.3.3.10.1.1.0-1 WAS:
Insertion below object IS705-1619 Section Number: 20.3.3.10.1.1.0-1 WAS: <inserted object=""> Redlines:</inserted>

Users who use the ISM will need to know which GNSS system is to apply these parameters. Therefore, the first parameter is a four-bit ID that defines each system.

IS705-1621: Insertion after object IS705-1620
Section Number : 20.3.3.10.1.1.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS:
The four bits are defined as follows:
0000 = No Data Available
0001 = Galileo
0010 = GLONASS
0011 = BeiDou
0100 = GPS
0101 = SBAS
0110 = QZSS
0111 = IRNSS
1000 through 1111 = Reserved for other systems
Rationale : Bit Definition for the Constellation ID
IS705-1661 : Insertion after object IS705-1621
Section Number : 20.3.3.10.1.1.0-3
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: If users see four bits of '0000', users will ignore the entire ISM.
Rationale: Statement that gives guidance to the users to ignore the ISM if they get a "0000".

IS705-1622 : Insertion after object IS705-1619
Section Number : 20.3.3.10.1.2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Object Heading : ISM Effectivity Time Stamp Week Number
Rationale : ISM Time Stamp Header
IS705-1623 : Insertion below object IS705-1622
Section Number : 20.3.3.10.1.2.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
${f IS}$: Bits 43 through 55 of Message Type 40 shall provide the ISM Week Number (WN $_{ISM}$) applicable to the start of the time of validity for a given ISM data issue.
Rationale: Users who use the ISM will need to know the time the parameters are created. This parameter in terms of weeks does so.

IS705-1624:
Insertion after object IS705-1623
Section Number : 20.3.3.10.1.2.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS:
This parameter describes the time stamp, in terms of weeks, for the ISM parameters.
Rationale: Users who use the ISM will need to know the time the parameters are created. This parameter in terms of weeks does so.
IS705-1625 : Insertion after object IS705-1622
Section Number : 20.3.3.10.1.3
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Object Heading : ISM Effectivity Time Stamp Time of Week
Rationale : ISM Time Stamp Header

IS705-1634: Insertion after object IS705-1625
Section Number : 20.3.3.10.1.4
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: Correlation Time Constant
Rationale : tcorrel header
IS705-1635 : Insertion below object IS705-1634
Section Number: 20.3.3.10.1.4.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
${f IS}$: Bits 62 through 64 of Message Type 40 shall provide the assumed Correlation Time Constant (t_{correl}) value for the ARAIM at the current time for the associated GNSS constellation.
Rationale: This parameter is used for the ARAIM algorithm to find an integrity solution

IS705-1660 : Insertion after object IS705-1635
Section Number: 20.3.3.10.1.4.0-2
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
000 = 0.25 hours
001 = 0.67 hours
010 = 1.0 hours
011 = 1.5 hours
100 = 3.0 hours
101 = 6.0 hours
110 = 12.0 hours
111 = RESERVED
Rationale: Bit definitions that map to the different time constants
IS705-1649 : Insertion after object IS705-1634
Section Number: 20.3.3.10.1.5
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: Additive Term for Nominal Pseudorange Error Bias
Rationale : Additive Term Header

IS705-1650 :
Insertion below object IS705-1649
Section Number: 20.3.3.10.1.5.0-1
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Bits 65 through 67 of Message Type 40 shall provide the assumed Additive Term (b_{nom0}) value for ARAIM at the current time for the associated GNSS constellation.
Rationale: This parameter is used for the ARAIM algorithm to find an integrity solution
IS705-1651 : Insertion after object IS705-1650
Section Number : 20.3.3.10.1.5.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
000 = 0.00 meters
001 = 0.25 meters
010 = 0.50 meters
011 = 0.75 meters
100 = 1.00 meters
101 = 1.25 meters
110 = 1.50 meters
111 = 2.00 meters
Rationale: Bit definitions that map to the different terms

IS705-1652 : Insertion after object IS705-1649				
Section Number : 10.3.3.10.1.6				
WAS : <inserted object=""></inserted>				
Redlines : <inserted object=""></inserted>				
IS : Object Heading : Scalar Term for Nominal Pseudorange Error Bias				
Rationale : Scalar Term Header				
IS705-1653 : Insertion below object IS705-1652				
Section Number : 20.3.3.10.1.6.0-1				
WAS : <inserted object=""></inserted>				
Redlines : <inserted object=""></inserted>				
IS : Bits 68 through 70 of Message Type 40 shall provide the assumed Scalar Term (Υ _{nom}) value for ARAIM at the current time for the associated GNSS constellation.				
Rationale: This parameter is used for the ARAIM algorithm to find an integrity solution				

IS705-1654 : Insertion after object IS705-1653
Section Number: 20.3.3.10.1.6.0-2
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
000 = 0.00
001 = 0.25
010 = 0.50
011 = 0.75
100 = 1.00
101 = 1.25
110 = 1.50
111 = 2.00
Rationale : Bit definitions that map to the different terms
IS705-1643 : Insertion after object IS705-1652
Section Number : 20.3.3.10.1.7
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Object Heading : Satellite Fault Probability
Rationale : Psat Header

IS705-1644: Insertion below object IS705-1643
Section Number : 20.3.3.10.1.7.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
$\textbf{IS}: \\$ Bits 71 through 73 of Message Type 40 shall provide the assumed Satellite Fault Probability (Psat) value for ARAIM at the current time for the associated GNSS constellation.
Rationale : This parameter is used for the ARAIM algorithm to find an integrity solution
IS705-1645 : Insertion after object IS705-1644
Section Number : 20.3.3.10.1.7.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
$000 = 1 \times 10^{-3} / \text{hours}$
$001 = 1 \times 10^{-4} / \text{hours}$
010 = 1 x 10 ⁻⁵ /hours
011 = 1 x 10 ⁻⁶ /hours
$100 = 1 \times 10^{-7} / \text{hours}$
101 = 1 x 10 ⁻⁸ /hours
110 = 1 x 10 ⁻⁹ /hours
111 = RESERVED

Bit definitions that map to the different terms

IS705-1631 : Insertion after object IS705-1643
Section Number : 20.3.3.10.1.8
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Object Heading : Constellation Fault Probability
Rationale : Pconst Header
IS705-1632 : Insertion below object IS705-1631
Section Number : 20.3.3.10.1.8.0-1
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Bits 74 through 76 of Message Type 40 shall provide the assumed Constellation Fault Probability (P _{const}) value for ARAIM at the current time for the associated GNSS constellation.
Rationale: This parameter is used for the ARAIM algorithm to find an integrity solution

IS705-1633 : Insertion after object IS705-1632
Section Number : 20.3.3.10.1.8.0-2
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
$000 = 1 \times 10^{-3} / \text{hours}$
$001 = 1 \times 10^{-4} / \text{hours}$
$010 = 1 \times 10^{-5}$ /hours
$011 = 1 \times 10^{-6}$ /hours
$100 = 1 \times 10^{-7}$ /hours
$101 = 1 \times 10^{-8}$ /hours
110 = 1 x 10 ⁻⁹ /hours
111 = RESERVED
Rationale : Bit definitions that map to the different terms
IS705-1646 : Insertion after object IS705-1631
Section Number : 20.3.3.10.1.9
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS : Object Heading : Mean Fault Duration
Rationale : MFD Header

IS705-1647: Insertion below object IS705-1646
Section Number : 20.3.3.10.1.9.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Bits 77 through 79 of Message Type 40 shall provide the assumed Mean Fault Duration (MFD) value for ARAIM at the current time for the associated GNSS constellation.
Rationale: This parameter is used for the ARAIM algorithm to find an integrity solution
IS705-1648 : Insertion after object IS705-1647
Section Number: 20.3.3.10.1.9.0-2
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: The three bits are defined as follows:
000 = 0.25 hours
001 = 0.5 hours
010 = 1.0 hours
011 = 1.5 hours
100 = 2.0 hours
101 = 4.0 hours
110 = 10.0 hours
111 = 24.0 hours
Rationale: Bit definitions that map to the different terms

IS705-1628: Insertion after object IS705-1646
Section Number : 20.3.3.10.1.10
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: Service Level
Rationale : Service Level Header
IS705-1629 : Insertion below object IS705-1628
Section Number: 20.3.3.10.1.10.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Bits 80 through 82 of Message Type 40 shall provide the Service Level, as described in Table 20-XIb, applicable to a given page of the ISM data issue.

Parameter will help the user determine what type of ARAIM these parameters can be used for (eg H-ARAIM or V-ARAIM).

S705-1630 :
Insertion after object IS705-1629
Section Number : 20.3.3.10.1.10.0-2
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
S : Three bits are allocated to the four identified service levels as follows:
000 = Level 1
001 = Level 2
010 = Level 3
011 = Level 4
100 to 111 = Reserved for future use
Rationale: Bit definitions that map to the specific Service Levels. There are Reserved Bits for a future type of level.
S705-1659 : Insertion after object IS705-1630
Section Number : 20.3.3.10.1.10.0-4
WAS : <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
I S : Table 20-XIb - Service Level
Rationale : Table Caption

IS705-1657:

Insertion after object IS705-1659

Section Number: 20.3.3.10.1.10.0-5

WAS:

<INSERTED OBJECT>

Redlines:

<INSERTED OBJECT>

IS:

Service Level	Severity	Description
Level 1	No Data Available	Service Level indicates that users may resort to the Performance Values for integrity solutions instead of the ISM. Users should not use ISM
Level 2	Non-Safety of Life Use (Minor)	Uncertified ARAIM
Level 3	Safety of Life Use (Major)	Service Level indicates that the user should only use these parameters for the applications requiring integrity less than or equivalent to H-ARAIM solutions.
Level 4	Safety of Life Use (Hazardous)	Service Level indicates that the user should only use these parameters for the applications requiring integrity less than or equivalent to V-ARAIM solutions.

Object Type : Table

Rationale:

Table gets more specific on each level. The last column is intended to give more guidance to the user on what to do for each level.

IS705-1640: Insertion after object IS705-1628
Section Number : 20.3.3.10.1.11
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Object Heading: Satellite Mask
Rationale : Mask Header
IS705-1641 : Insertion below object IS705-1640
Section Number: 20.3.3.10.1.11.0-1
WAS: <inserted object=""></inserted>
Redlines : <inserted object=""></inserted>
IS: Bits 83 through 145 of Message Type 40 shall provide the PRN inclusion mask. Refer to Table 20-XIc for complete GNSS PRN mapping.
Pationalo :

Each bit of the Mask pertains to a single GNSS PRN. The table gets more specific.

IS705-1642 :
Insertion after object IS705-1641
Section Number :
20.3.3.10.1.11.0-2
WAS:
<inserted object=""></inserted>
Redlines:
<inserted object=""></inserted>
IS:
The applicability of each PRN is indicated by:
0 = Information in the current ISM does not apply to this PRN
1 = Information in the current ISM does apply to this PRN
Rationale :
Defining the difference between '0' and '1'.
IS705-1662 :
Insertion after object IS705-1642
Section Number :
20.3.3.10.1.11.0-5
WAS:
<inserted object=""></inserted>
Redlines :
<inserted object=""></inserted>
IS:
Table 20-XIc PRN Mapping
Rationale :
Table Caption

IS705-1663:

Insertion after object IS705-1662

Section Number: 20.3.3.10.1.11.0-6

WAS:

<INSERTED OBJECT>

Redlines:

_<INSERTED OBJECT>

IS:

Bits	Galileo	GLONASS	BeiDou	GPS	SBAS	QZSS	IRNSS
83	SVID 1	Freq. 1	RCN 1	PRN 1	PRN 120	PRN 183	PRN ID-1
84	SVID 2	Freq. 2	RCN 2	PRN 2	PRN 121	PRN 184	PRN ID-2
85	SVID 3	Freq. 3	RCN 3	PRN 3	PRN 122	PRN 185	PRN ID-3
86	SVID 4	Freq. 4	RCN 4	PRN 4	PRN 123	PRN 186	PRN ID-4
87	SVID 5	Freq. 5	RCN 5	PRN 5	PRN 124	PRN 187	PRN ID-5
88	SVID 6	Freq. 6	RCN 6	PRN 6	PRN 125	PRN 188	PRN ID-6
89	SVID 7	Freq. 7	RCN 7	PRN 7	PRN 126	PRN 189	PRN ID-7
90	SVID 8	Freq. 8	RCN 8	PRN 8	PRN 127	PRN 190	Reserved
91	SVID 9	Freq. 9	RCN 9	PRN 9	PRN 128	PRN 191	Reserved
92	SVID 10	Freq. 10	RCN 10	PRN 10	PRN 129	PRN 192	Reserved
93	SVID 11	Freq. 11	RCN 11	PRN 11	PRN 130	PRN 193	Reserved
94	SVID 12	Freq. 12	RCN 12	PRN 12	PRN 131	PRN 194	Reserved
95	SVID 13	Freq. 13	RCN 13	PRN 13	PRN 132	PRN 195	Reserved
96	SVID 14	Freq. 14	RCN 14	PRN 14	PRN 133	PRN 196	Reserved
97	SVID 15	Freq. 15	RCN 15	PRN 15	PRN 134	PRN 197	Reserved
98	SVID 16	Freq. 16	RCN 16	PRN 16	PRN 135	PRN 198	Reserved
99	SVID 17	Freq. 17	RCN 17	PRN 17	PRN 136	PRN 199	Reserved
100	SVID 18	Freq. 18	RCN 18	PRN 18	PRN 137	PRN 200	Reserved
101	SVID 19	Freq. 19	RCN 19	PRN 19	PRN 138	PRN 201	Reserved
102	SVID 20	Freq. 20	RCN 20	PRN 20	PRN 139	PRN 202	Reserved
103	SVID 21	Freq. 21	RCN 21	PRN 21	PRN 140	Reserved	Reserved
104	SVID 22	Freq. 22	RCN 22	PRN 22	PRN 141	Reserved	Reserved
105	SVID 23	Freq. 23	RCN 23	PRN 23	PRN 142	Reserved	Reserved
106	SVID 24	Freq. 24	RCN 24	PRN 24	PRN 143	Reserved	Reserved
107	SVID 25	Freq. 25	RCN 25	PRN 25	PRN 144	Reserved	Reserved
108	SVID 26	Freq. 26	RCN 26	PRN 26	PRN 145	Reserved	Reserved
109	SVID 27	Freq. 27	RCN 27	PRN 27	PRN 146	Reserved	Reserved
110	SVID 28	Freq. 28	RCN 28	PRN 28	PRN 147	Reserved	Reserved
111	SVID 29	Freq. 29	RCN 29	PRN 29	PRN 148	Reserved	Reserved
112	SVID 30	Freq. 30	RCN 30	PRN 30	PRN 149	Reserved	Reserved
113	SVID 31	Freq. 31	RCN 31	PRN 31	PRN 150	Reserved	Reserved
114	SVID 32	Freq. 32	RCN 32	PRN 32	PRN 151	Reserved	Reserved
115	SVID 33	Reserved	RCN 33	PRN 33	PRN 152	Reserved	Reserved
116	SVID 34	Reserved	RCN 34	PRN 34	PRN 153	Reserved	Reserved
117	SVID 35	Reserved	RCN 35	PRN 35	PRN 154	Reserved	Reserved
118	SVID 36	Reserved	RCN 36	PRN 36	PRN 155	Reserved	Reserved
119	Reserved	Reserved	RCN 37	PRN 37	PRN 156	Reserved	Reserved
120	Reserved	Reserved	Reserved	PRN 38	PRN 157	Reserved	Reserved
121	Reserved	Reserved	Reserved	PRN 39	PRN 158	Reserved	Reserved
122	Reserved	Reserved	Reserved	PRN 40	Reserved	Reserved	Reserved
123	Reserved	Reserved	Reserved	PRN 41	Reserved	Reserved	Reserved
124	Reserved	Reserved	Reserved	PRN 42	Reserved	Reserved	Reserved
125	Reserved	Reserved	Reserved	PRN 43	Reserved	Reserved	Reserved
126	Reserved	Reserved	Reserved	PRN 44	Reserved	Reserved	Reserved
127	Reserved	Reserved	Reserved	PRN 45	Reserved	Reserved	Reserved

128	Reserved	Reserved	Reserved	PRN 46	Reserved	Reserved	Reserved
129	Reserved	Reserved	Reserved	PRN 47	Reserved	Reserved	Reserved
130	Reserved	Reserved	Reserved	PRN 48	Reserved	Reserved	Reserved
131	Reserved	Reserved	Reserved	PRN 49	Reserved	Reserved	Reserved
132	Reserved	Reserved	Reserved	PRN 50	Reserved	Reserved	Reserved
133	Reserved	Reserved	Reserved	PRN 51	Reserved	Reserved	Reserved
134	Reserved	Reserved	Reserved	PRN 52	Reserved	Reserved	Reserved
135	Reserved	Reserved	Reserved	PRN 53	Reserved	Reserved	Reserved
136	Reserved	Reserved	Reserved	PRN 54	Reserved	Reserved	Reserved
137	Reserved	Reserved	Reserved	PRN 55	Reserved	Reserved	Reserved
138	Reserved	Reserved	Reserved	PRN 56	Reserved	Reserved	Reserved
139	Reserved	Reserved	Reserved	PRN 57	Reserved	Reserved	Reserved
140	Reserved	Reserved	Reserved	PRN 58	Reserved	Reserved	Reserved
141	Reserved	Reserved	Reserved	PRN 59	Reserved	Reserved	Reserved
142	Reserved	Reserved	Reserved	PRN 60	Reserved	Reserved	Reserved
143	Reserved	Reserved	Reserved	PRN 61	Reserved	Reserved	Reserved
144	Reserved	Reserved	Reserved	PRN 62	Reserved	Reserved	Reserved
145	Reserved	Reserved	Reserved	PRN 63	Reserved	Reserved	Reserved

SVID = Space Vehicle ID

Freq. = Carrier Frequency Number RCN = Ranging Code Number

PRN = Pseudorandom Noise Number

Rationale:

Added the table that specifically maps the Mask bits to individual SV IDs for different GNSS.

IS705-1664:

Insertion after object IS705-1663

Section Number:

20.3.3.10.1.12

WAS:

<INSERTED OBJECT>

Redlines:

<INSERTED OBJECT>

IS:

Object Heading: Integrity Support Message Cyclic Redundancy Check

Rationale:

Add Header for ISM CRC

1	IS7	റ	1	_	_	
	. 7 /	.,	 	. 7		

Insertion after object IS705-1664

Section Number:

20.3.3.10.1.12.0-1

WAS:

<INSERTED OBJECT>

Redlines:

<INSERTED OBJECT>

IS:

Bits 245 through 276 of MT-40 are a 32-bit Cyclic Redundancy Check (CRC) specific to the ISM parameters. The ISM CRC will cover only the ISM parameters in Message Type 40, (Bits 39 to 244). Refer to GNSS-Based Precision Approach Local Area Augmentation System (LAAS) Signal-in-Space Interface Control Document for more details on the ISM CRC.

Rationale:

The ISM CRC is an added security measure to check the accuracy of the ISM data.

IS705-371:

Section Number:

20.3.4.1.0-3

WAS:

Message Data	Message Type Number	Maximum Broadcast Intervals †		
Ephemeris	10 & 11	24 sec		
Clock	Type 30's	24 sec		
ISC, IONO	30*	144 sec		
Reduced Almanac	31* or 12	10 min**,***		
Midi Almanac	37*	60 min**		
ЕОР	32*	15 min****		
UTC	33*	144 sec		
Diff Correction	34* or 13 & 14	15 min***,***		
GGTO	35*	144 sec***		
Text 36* or 15		As needed****		

^{*} Also contains SV clock correction parameters.

^{**} Complete set of SVs in the constellation.

^{***} When Differential Corrections are available.

^{****} Optional (interval applies if/when broadcast).

[†] The intervals specified are maximum. As such, the broadcast intervals may be shorter than the specified value.

Redlines:

Message Data	Message Type Number	Maximum Broadcast Intervals †		
Ephemeris	10 & 11	24 sec		
Clock	Type 30's	24 sec		
ISC, IONO	30*	144 sec		
Reduced Almanac	31* or 12	10 min**,***		
Midi Almanac	37*	60 min**		
ЕОР	32*	15 min****		
UTC	33*	144 sec		
Diff Correction	34* or 13 & 14	15 min***,***		
GGTO	35*	144 sec***		
Text	36* or 15	As needed****		
Integrity Support Message +	<u>40</u>	144 sec***		

^{*} Also contains SV clock correction parameters.

^{**} Complete set of SVs in the constellation.

^{***} When Differential Corrections are available.

^{****} Optional (interval applies if/when broadcast).

⁺ One ISM per maximum broadcast interval; However, users can accept multiple ISMs from any SVs. Users are not required to collect them all, but may need to.

[†] The intervals specified are maximum. As such, the broadcast intervals may be shorter than the specified value.

Message Data	Message Type Number	Maximum Broadcast Intervals †		
Ephemeris	10 & 11	24 sec		
Clock	Type 30's	24 sec		
ISC, IONO	30*	144 sec		
Reduced Almanac	31* or 12	10 min**,***		
Midi Almanac	37*	60 min**		
ЕОР	32*	15 min****		
UTC	33*	144 sec		
Diff Correction	34* or 13 & 14	15 min***,***		
GGTO	35*	144 sec***		
Text	36* or 15	As needed****		
Integrity Support Message +	40	144 sec***		

^{*} Also contains SV clock correction parameters.

Adding MT40 to the broadcast interval table. Made an extra note to notify the user that only ISM will be found in the maximum broadcast interval. However, an entire set will take longer.

^{**} Complete set of SVs in the constellation.

^{***} When Differential Corrections are available.

^{****} Optional (interval applies if/when broadcast).

⁺ One ISM per maximum broadcast interval; However, users can accept multiple ISMs from any SVs. Users are not required to collect them all, but may need to.

[†] The intervals specified are maximum. As such, the broadcast intervals may be shorter than the specified value.