Change Topic: Public Signals in Space Requirements Disconnects

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This change package accommodates the text changes to support the proposed solution (see table below) within the public Signals-in-Space (SiS) documents. All comments must be submitted in Comments Resolution Matrix (CRM) form.

The columns in the WAS/IS table following this page are defined below:

Section Number: This number indicates the location of the text change within the document.

Proposed Heading: Contains existing and/or proposed changes to section titles and/or the titles to new sections

(WAS) <Document Title>: Contains the baseline text of the impacted document.

Proposed Object Text: Contains proposed changes to baseline text.

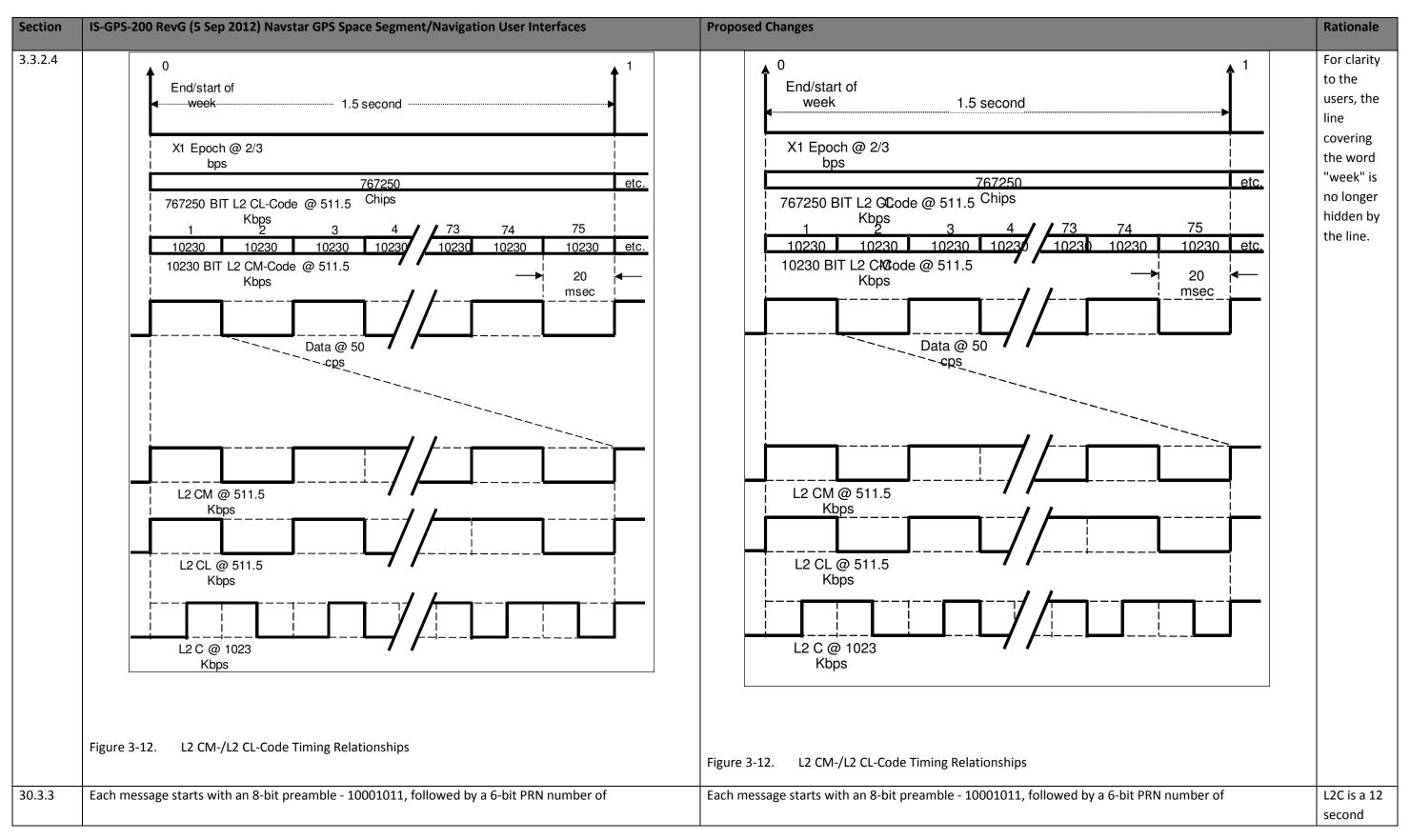
PROBLEM STATEMENT:

The current public signals in space documents contain incorrect information (L2C message duration, GNSS ID bit assignments), and missing information (L5 ellipticity values). If these disconnects are not resolved, receiver manufacturers will have issues designing to incorrect requirements and the Directorate will be misrepresenting the current and future GPS system performance in a public document.

SOLUTION: (Proposed)

Resolve the incorrect (L2C message duration, GNSS ID bit assignments), and missing (L5 ellipticity values) requirements in the public signals in space documents

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Section	IS-GPS-200 RevG (5 Sep 2012) Navstar GPS Space Segment/Navigation User Interfaces					Proposed Changes				Rationale			
	the transmitti	ng SV, a 6-bit message type ID with	a range of	0 (000000) to 63	(111111), and	t	the transmitting SV, a 6-bit message type ID with a range of 0 (000000) to 63 (111111), and					message,	
	the 17-bit message time of week (TOW) count. When the value of the message TOW count is						the 17-bit message time of week (TOW) count. When the value of the message TOW count is				not a 6 second		
	multiplied by 6, it represents SV time in seconds at the start of the next 6-second message.						multiplied by 6, it represents SV time in seconds at the start of the next 12-second message.				message. L5 is a 6		
	An "alert" flag, when raised (bit 38 = "1"), indicates to the user that the signal URA							An "alert" flag, when raised (bit 38 = "1"), indicates to the user that the signal URA				second	
	components may be worse than indicated in the associated message types and that he shall							components may be worse than indicated in the associated message types and that he shall				message.	
	use at his own risk. For each default message (Message Type 0), bits 39 through 276 shall be							use at his own risk. For each default message (Message Type 0), bits 39 through 276 shall be					
	alternating ones and zeros and the message shall contain a proper CRC parity block.							alternating ones and zeros and the message shall contain a proper CRC parity block.					
30.3.3.1.1							Bit 273 of Message Type 10 indicates the phase relationship between L2C and P(Y) as specified in section 3.3.1.5.1 of IS-GPS-200.						Maintain definition consistency across the Public SIS documents.
30.3.3.6.2	Table 30-IX. UTC Parameters						Table 30-IX. UTC Parameters				The		
		Parameter	No. of Bits**	Scale Factor (LSB)	Effective Range***	Units		Parameter	No. of Bits**	Scale Factor (LSB)	Effective Range***	Units	number of bits assigned to
	A _{0-n}	Bias coefficient of GPS time scale relative to UTC time scale	16*	2 ⁻³⁵		Seconds	A _{0-n}	Bias coefficient of GPS time scale relative to UTC time scale	16*	2 ⁻³⁵		Seconds	the WNLSF parameter is incorrect.
	A_{1-n}	Drift coefficient of GPS time scale relative to UTC time scale	13*	2 ⁻⁵¹		sec/sec	A_{1-n}	Drift coefficient of GPS time scale relative to UTC time scale	13*	2 ⁻⁵¹		sec/sec	In order to
	A _{2-n}	Drift rate correction coefficient of GPS time scale relative to UTC time scale	7*	2 ⁻⁶⁸		sec/sec ²	A _{2-n}	Drift rate correction coefficient of GPS time scale relative to UTC time scale	7*	2 ⁻⁶⁸		sec/sec ²	consistent with Figure 30-6, as
	Δt_{LS}	Current or past leap second count	8*	1		seconds	$\Delta t_{ m LS}$	Current or past leap second count	8*	1		seconds	well as the
	t _{ot}	Time data reference Time of Week	16	2^4	604,784	seconds	t _{ot}	Time data reference Time of Week	16	2^4	604,784	seconds	bit lengths for WNLSF
	WN _{ot}	Time data reference Week Number	13	1		weeks	WN _{ot}	Time data reference Week Number	13	1		weeks	in IS-GPS-
	WN _{LSF}	Leap second reference Week Number	8	1		weeks	WN _{LSF}	Leap second reference Week Number	13	1		weeks	705 and IS- GPS-800,
	DN	Leap second reference Day Number	4*** 8*	1		days seconds	DN	Leap second reference Day Number	4****	1		days	the bit length has
	$\Delta t_{ m LSF}$	ramor		<u> </u>		Seconds	$\Delta t_{ m LSF}$	Tvalliooi	8*	1		seconds	been

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	* Parameters so indicated shall be two's complement with the sign bit (+ or -) occupying the MSB; ** See Figure 30-6 for complete bit allocation; *** Unless otherwise indicated in this column, effective range is the maximum range attainable with indicated bit allocation and scale factor; **** Right justified.	* Parameters so indicated shall be two's complement with the sign bit (+ or -) occupying the MSB; ** See Figure 30-6 for complete bit allocation; Unless otherwise indicated in this column, effective range is the maximum range attainable with indicated bit allocation and scale factor; **** Right justified.	updated to be 13 bits, not 8 bits. Also, the DN entry in the No. of Bits column should be "4***", not "4***" (missing one asterisk).		
30.3.3.8.1	Message Type 35 provides SV clock correction parameters (ref. Section 30.3.3.2) and also, shall contain the parameters related to correlating GPS time with other GNSS time. Bits 155 through 157 of message type 35 shall identify the other GPS like navigation system to which the offset data applies. The three bits are defined as follows; 000 = no data available, 001 = Galileo, 010 = GLONASS,	Message Type 35 provides SV clock correction parameters (ref. Section 30.3.3.2) and also, shall contain the parameters related to correlating GPS time with other GNSS time. Bits 157 through 159 of message type 35 shall identify the other GPS like navigation system to which the offset data applies. The three bits are defined as follows;			
	011 through 111 = reserved for other systems.	000 = no data available, 001 = Galileo, 010 = GLONASS,	We believe that the IS- 200, Figure 30-8 is correct. It		
		011 through 111 = reserved for other systems.	shows that GNSS ID starts at bit 157 and is 3 bits long. The text in Section 30.3.3.8.1 should match the bits layout in the		

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			figure.