



Why Wait? Real-Time GNSS Monitoring for Infrastructure Protection and a Perspective on Galileo vs GPS

Yoaz Bar-Sever

(Yoaz.Bar-Sever@jpl.nasa.gov)

Jet Propulsion Laboratory California Institute of Technology

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Providing mission-critical, real-time services, 24/7, since 2000 Full GNSS capabilities: GPS, GLONASS, BeiDou, Galileo, QZSS, NAVIC



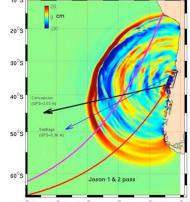
Prototype system and testbed for Next Generation GPS Control Segment (OCX)

Time-critical environmental monitoring services

Repeat path interferometry with UAV-SAR



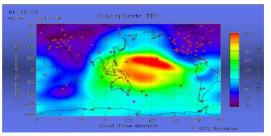
Earthquake monitoring and tsunami prediction



Radio Occultations for weather forecasting



Space weather monitoring





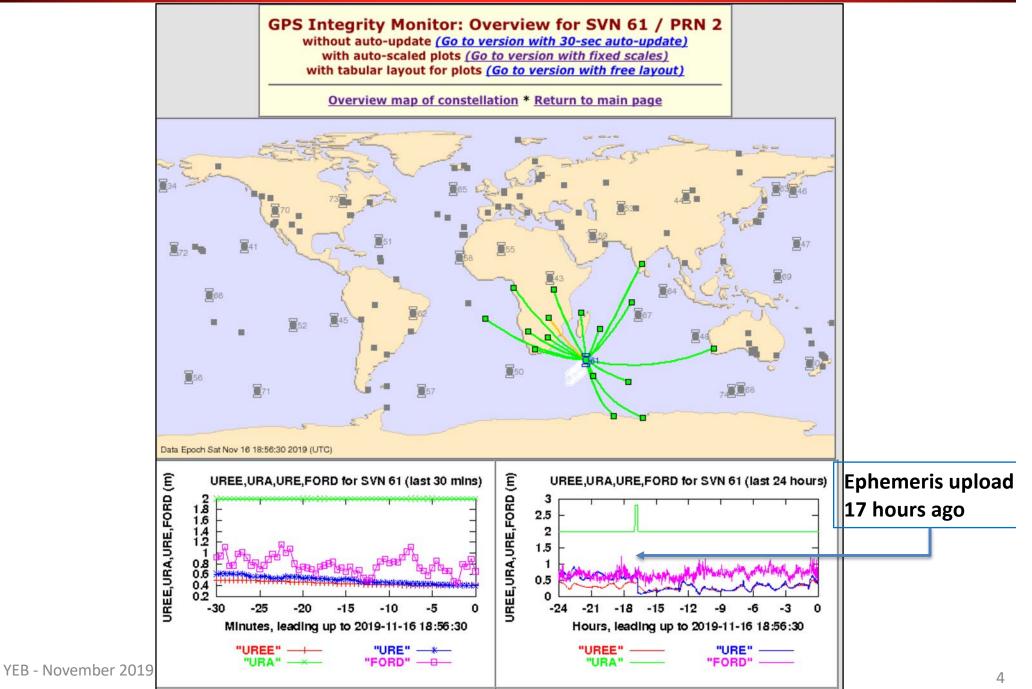
Two Decades of GPS Performance Monitoring for USAF GDG

RMS URE (this snapshot): 0.53 m					٦	32 GPS in view (108 sites reporting) Page generated on Sat Nov 16 18:31:28 2019 (UTC) Data Epoch: 28 seconds prior to page generation, Sat Nov 16 18:31:00 2019 (UTC)									Mean AOD (Age of Data)							
Median URE: 0.33 m						GPS Integrity Monitor: Table sorted by SVN without auto-update (Go to version with 30-sec auto-update)											11.5 hours					
Healthy sats only		-	_		Pe	rforma	nce me		-		ock err			UTC Model			k Stati	istics				
	SVN (2)	PRN (?)	(?)	Block (?)	URE	FORD (plot,?)	URA	URE/URA	UREE	CLK	RSS	RAC	SIGMA (plot,?)	dUTC dtRef (plot,?) (plot,?)	Total (plot,?)		Bad	Missing	(plot,?)	AOD (plot,?)	Health (plot,?)	SVN (2)
	41	14	D-6 F-1	IIA IIR	0.12	0.86	2.00	0.06	0.06	0.08	0.43	plot	0.00	-0.297 -46.4	<u>30</u> 22	24	0	<u>0</u>	<u>20</u>	<u>7.0</u>	<u>0</u>	41
	43	13	F-2	IIR	0.11	1.05	2.00	0.06	0.10	0.04	0.74	plot	0.00	-0.144 -22.5	43	43	0	0	24	22.5	Q	43
	44	28	B-3	IIR	1.55	<u>0.84</u>	4.00	<u>0.39</u>	<u>0.11</u>	-1.44	<u>0.28</u>	plot	0.00	-0.297 -46.4	<u>39</u>	<u>39</u>	<u>0</u>	<u>0</u>	27	<u>20.3</u>	Q	44
	<u>45</u>	21	D-3	IIR	0.17	0.96	2.00	0.09	0.17	-0.09	1.19	plot	0.00	<u>-0.297</u> <u>-46.4</u>	24	24	0	0	20	<u>17.8</u>	<u>0</u>	45
	<u>46</u> <u>47</u>	11 22	D-2 E-2	IIR IIR	<u>1.05</u> 0.41	<u>1.78</u> 0.96	2.00 2.00	0.53 0.20	0.26 0.07	<u>0.81</u> -0.38	0.87 0.46	plot plot	0.00	-0.297 -46.4 -0.297 -46.4	29 31	27 30	<u>0</u>	2	28 23	<u>11.5</u> <u>19.3</u>	<u>0</u> 0	46 47
Average	48	Z		IIR-M	0.04	0.80	2.00	0.02	0.21	-0.24	0.30	plot	0.00	-0.148 -46.4	26	26	0	1 0	22	0.8	0	48
U	50	5	E-3	IIR-M	0.43	0.76	2.00	0.22	0.18	-0.27	0.62	plot	0.01	-0.297 -46.4	24	23	0	1	13	8.3	0	50
observability:	<u>51</u>	20	E-7	IIR	0.34	0.86	2.00	0.17	0.10	-0.26	0.49	plot	0.00	-0.148 -46.4	<u>43</u>	43	<u>0</u>	<u>o</u>	24	<u>3.5</u>	Q	51
28 sites	<u>52</u>	31		IIR-M	0.86	0.51	2.00	0.43	<u>0.21</u>	0.67	0.75	plot	0.00	<u>-0.297</u> <u>-46.4</u>	<u>13</u>	13	0	<u>0</u>	17	<u>11.3</u>	Q	<u>52</u>
	53	17		IIR-M	0.45	0.51	2.00	0.22	0.27	0.18	0.47	plot	0.00	<u>-0.297</u> <u>-46.4</u>	42	41	0	1	31	7.5	0	53
	<u>55</u> 56	<u>15</u> 16	B-1	IIR-M IIR	0.33 0.25	0.49 0.76	2.00 2.00	0.17 0.12	0.24 0.13	<u>0.17</u> -0.13	<u>1.65</u> 0.69	plot plot	<u>0.00</u>	<u>-0.297</u> <u>-46.4</u> -0.297 <u>-46.4</u>	42 20	42 19	0	0 1	23 11	<u>14.3</u> <u>8.8</u>	<u>0</u> 0	<u>55</u> 56
Minimum	57	29		IIR-M	0.65	0.86	2.00	0.33	0.21	-0.67	1.47	plot	0.01	-0.297 -46.4	16	16	0	Ō	2	17.5	Q	57
	58	12	B-4	IIR-M	0.09	1.02	2.00	0.05	0.28	0.24	0.68	plot	0.00	-0.144 -22.5	41	41	<u>0</u>	<u>o</u>	23	22.3	Q	58
observability:	<u>59</u>	<u>19</u>	C-3	IIR	<u>0.09</u>	<u>0.88</u>	2.00	0.05	0.22	<u>-0.30</u>	<u>0.37</u>	plot	0.00	<u>-0.297</u> <u>-46.4</u>	<u>36</u>	<u>36</u>	<u>0</u>	<u>0</u>	25	<u>9.5</u>	Q	<u>59</u>
13 sites	<u>60</u>	23	F-4	IIR	0.28	0.47	2.00	0.14	0.14	0.20	1.01	plot	0.00	-0.297 -46.4	21	21	0	0	<u>6</u>	17.8	Q	<u>60</u>
	<u>61</u> 62	2 25	D-1 B-2	IIR IIF	0.56 0.18	0.82 0.43	2.00 2.00	0.28 0.09	<u>0.49</u> 0.21	<u>-0.11</u> -0.06	2.91 1.22	plot plot	<u>0.01</u> 0.01	<u>-0.297</u> <u>-46.4</u> -0.297 -46.4	20 19	<u>19</u> <u>19</u>	0	1 0	11 12	<u>17.0</u> <u>19.8</u>	0 0	<u>61</u> <u>62</u>
	63	1	D-2	IIF	0.07	0.39	2.00	0.03	0.15	-0.21	0.29	plot	0.00	-0.297 -46.4	28	26	0	2	28	<u>6.0</u>	Q	63
	64	30	A-3	IIF	0.35	0.71	2.00	0.18	0.17	0.18	0.31	plot	0.00	-0.297 -46.4	28	27	0	1	29	14.0	Q	64
	<u>65</u>	24	A-1	IIF	1.12	1.08	2.00	0.56	0.26	0.89	0.95	plot	0.00	-0.148 -46.4	48	48	Q	<u>o</u>	30	2.3	Q	<u>65</u>
	<u>66</u>	27	C-2	IIF	<u>0.33</u>	<u>0.71</u>	2.00	<u>0.16</u>	0.09	<u>-0.24</u>	<u>0.20</u>	plot	0.00	<u>-0.148</u> <u>-46.4</u>	24	24	<u>0</u>	<u>o</u>	23	<u>3.3</u>	Q	<u>66</u>
	67	6	D-4	IIF	0.55	0.89	2.00	0.27	0.59	-0.05	1.59	plot	0.00	<u>-0.148</u> <u>-46.4</u>	26	24	0	2	14	0.5	0	67
	<u>68</u> 69	<u>9</u> 3	F-3 E-1	IIF IIF	0.17 0.25	0.59	2.00	0.08 0.13	0.04 0.24	<u>0.14</u> -0.02	0.26 1.72	plot plot	0.00	<u>-0.297</u> <u>-46.4</u> -0.297 <u>-46.4</u>	22 27	22 26	<u>0</u>	01	11 19	<u>4.5</u> <u>11.3</u>	<u>0</u> 0	<u>68</u> 69
	70	32	F-1	IIF	0.23	0.69	2.00	0.12	0.16	-0.16	1.14	plot	0.00	-0.297 -46.4	24	23	0	1	25	8.0	Q	70
	71	26	B-1	IIF	0.42	0.70	2.00	0.21	0.44	0.02	1.28	plot	0.00	-0.297 -46.4	22	22	0	0	10	16.5	0	<u>71</u>
	72	8	C-3	IIF	0.46	0.87	2.00	0.23	0.22	0.58	1.17	plot	0.00	<u>-0.297</u> <u>-46.4</u>	26	26	<u>0</u>	<u>0</u>	28	<u>16.3</u>	<u>0</u>	72
	<u>73</u>	<u>10</u>	E-2	IIF	<u>0.15</u>	<u>0.69</u>	<u>2.00</u>	0.07	0.16	<u>0.31</u>	<u>0.18</u>	plot	<u>0.00</u>	-0.297 -46.4	<u>45</u>	<u>44</u>	<u>0</u>	1	<u>31</u>	<u>4.5</u>	<u>0</u>	<u>73</u>
YEB - November 2019	SVN	PRN	F-3 Orbit	IIIA Block	URE	FORD	URA	URE/URA	UREE	CLK	6.10 <u>RSS</u>	RAC	<u>SIGMA</u>	<u>40.777</u> <u>121.6</u> <u>dUTC</u> <u>dtRef</u>	Total	Good	Bad	<u>9</u> Missing	BCE	AOD	<u>Health</u>	SVN 3



Large Footprint of GPS Satellite Signals and Dense Global Network are key to Resiliency of the GDGPS System







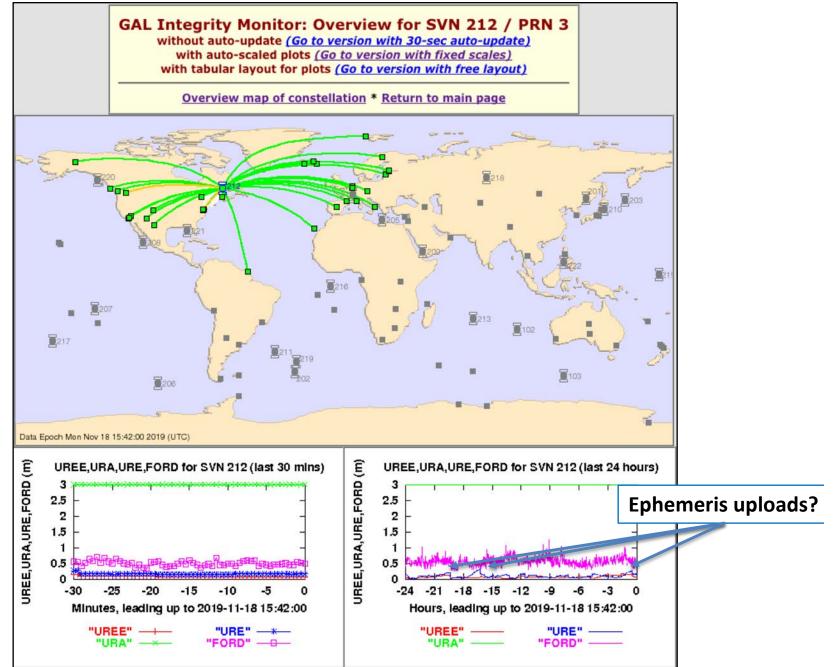


RMS URE (this sna		23 GAL in view (87 sites reporting)												Mean AOD							
0.44 m		Data	Page generated on Mon Nov 18 15:43:54 2019 (UTC) Data Epoch: 24 seconds prior to page generation, Mon Nov 18 15:43:30 2019 (UTC											C)	reported to						
	47			- 1	<u>.</u>														be <	1	nour
Median URE: 0.	Ι/	m		Т	GAL Integrity Monitor: Table sorted by SVN											InsideGNSS Sep/Oct 2018					
Healthy sats only			_		without auto-update (Go to version with 30-sec auto-update)										IIIS		s sep/	000 2018			
,				Per	erformance metrics			Orbit/Clock error metrics				Link Statistics									
	SVN (?)	PRN (?)	Block (?)		FORD (plot,?)		URE/URA (plot,?)	UREE				SIGMA (plot,?)		Good		Missing (plot,?)	BCE (plot,?)	AOD (plot,?)	Health (plot,?)	SVN (2)	
	102	12	IOV	0.73	0.56	3.00	0.24	0.03	0.70	0.09	plot	0.00	20	15	0	5	2	=	0	102	
	103		IOV	0.27	0.47		0.09	0.19	0.38	0.90	plot	0.00	14	10	0	4	5	-	<u>0</u>	103	
	201	18	FOCe	0.27	0.42	3.00	0.09	0.24	0.03	0.57	<u>pint</u>	0.00	15	8	0	2	2	- 2	1	201	
Average	202	14	FOCe	0.04	0.36	3.00	0.01	0.06	-0.07	0.24	<u>piet</u>	0.00	26	18	0	8	10	2	1	202	
observability:	203	<u>26</u> 24	FOC FOC	0.24 1.61	0.59 0.46	3.00 3.00	0.08 0.54	0.35 0.13	-0.12 1.50	0.45 0.59	plot plot	0.00	<u>18</u>	<u>15</u>	0	3	12	-	0	203	
•	205 206		FOC	0.05	0.40	3.00	0.02	0.06	-0.08	0.25	plot	<u>0.00</u> 0.00	<u>34</u> 18	<u>31</u> 17	<u>0</u> 0	<u>3</u> 1	<u>12</u> <u>6</u>		<u>0</u> 0	205 206	
20 sites (this	207	Z	FOC	0.07	0.61	3.00	0.02	0.08	0.06	0.50	plot	0.00	14	14	0	0	10	-	<u>0</u>	207	
snapshot)	208	8	FOC	0.17	0.40	3.00	0.06	0.08	-0.08	0.13	plot	0.00	23	21	<u>0</u>	2	14	- 2	<u>0</u>	208	
shapshoty	209	2	FOC	0.08	0.50	3.00	<u>0.03</u>	<u>0.04</u>	-0.09	0.24	plot	0.00	<u>35</u>	33	<u>0</u>	2	13	4	Q	<u>209</u>	
	210	a second	FOC	0.08	0.37	3.00	0.03	0.25	-0.18	0.43	plot	0.00	<u>16</u>	<u>14</u>	<u>0</u>	2	10		<u>0</u>	<u>210</u>	
Minimum	211	2	FOC	0.20	0.33	3.00	0.07	0.19	-0.01	0.20	plot	0.00	24	21	0	3	11	12	0	211	
-	212 213	<u>3</u> 4	FOC FOC	0.15 0.14	0.39 0.52	<u>3.00</u> <u>3.00</u>	<u>0.05</u> 0.05	0.06 0.11	<u>0.20</u> -0.25	0.29 0.17	plot plot	<u>0.00</u> 0.00	<u>36</u> 20	<u>34</u> <u>17</u>	0 0	<u>2</u> <u>3</u>	<u>15</u> <u>10</u>	÷.	<u>0</u> 0	212 213	
observability:	214	5	FOC	0.22	0.34	3.00	0.07	0.04	0.21	0.25	plot	0.00	32	31	0	1	14		0	214	
5 sites (this	215		FOC	0.02	0.48	3.00	0.01	0.09	-0.09	0.16	plot	0.00	15	12	0	3	2	-	0	215	
•	216	25	FOC	0.43	0.50	3.00	0.14	0.16	0.27	0.38	plot	0.00	<u>28</u>	28	<u>0</u>	<u>0</u>	13	2	Q	<u>216</u>	
snapshot)	217		FOC	<u>0.07</u>	0.72	3.00	0.02	<u>0.07</u>	-0.12	0.25	plot	0.00	12	<u>5</u>	<u>0</u>	Z	<u>5</u>		Q	<u>217</u>	
	218	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	FOC	<u>0.20</u>	0.60	3.00	<u>0.07</u>	0.05	0.22	0.32	plot	0.00	32	<u>30</u>	<u>0</u>	2	14	4	<u>0</u>	<u>218</u>	
	219		FOC	0.54	0.31	3.00	0.18	0.06	0.59	0.25	plot	0.00	26	21	0	5	10	-	0	219	
	220 221	<u>13</u> <u>15</u>	FOC FOC	0.06 0.19	0.68 0.73	<u>3.00</u> 3.00	0.02 0.06	0.07 0.12	0.01 0.30	0.31 0.30	plot plot	<u>0.00</u> 0.00	27 24	25 24	<u>0</u> 0	2	<u>18</u> 17	2 2	<u>0</u> 0	<u>220</u> 221	
	222		FOC	0.06	0.41	3.00	0.02	0.12	-0.14	0.44	plot	0.00	14	11	0	3	10		0	222	
	_		Block	URE	the state of the s	-	URE/URA	Concession in which the real of the local division in which the local division in which the local division is not the local division in the local division		RSS		SIGMA	Total		Bad		BCE	AOD	Health		
	-																				L



Galileo is Well Observed by the GDGPS System; Multiple Ephemeris Uploads Hardly Noticeable









																				_				
			35 BDS in view (69 sites reporting)																					
	Page generated on Sat Nov 16 19:40:24 2019 (UTC) Data Epoch: 24 seconds prior to page generation, Sat Nov 16 19:40:00 2019 (UTC)																							
	BDS Integrity Monitor: Table sorted by SVN without auto-update (Go to version with 30-sec auto-update)																							
10-10-10-10-10-10-10-10-10-10-10-10-10-1			Performance metrics Orbit/Clock error metrics Link Statistics																					
SVN		Block				URE/UR							Good				AOD	Health						
(?)	(?)	(<u>?</u>)	(<u>plot,?</u>)	(<u>plot,?</u>)	(plot,?)	(plot,?)	(plot,?)	(<u>plot,?</u>) (plot,?) (plot,?)	(<u>plot,?</u>)	No. of Concession, Name	(<u>plot,?</u>) (j	olot,?)	(plot,?)	(plot,?)	(<u>plot</u> ,?)	(<u>plot,?</u>)	(?)	-				
3	1	GEO-2	Ξ.	÷.	-	=	1.3	-	-	plot	-	<u>19</u>	<u>18</u>	<u>0</u>	1	<u>14</u>	<u>1.0</u>	<u>0</u>	3					
5		IGSO-2	<u>6.08</u>	2.97	4.00	1.52	<u>1.92</u>	-7.98	2.53	plot	0.00	<u>16</u>	15	0	1	Z	3.0	<u>0</u>	5					
6	4	GEO-2	1.29	2.77	4.00	0.32	3.81	-4.87	5.96	plot	0.00	18	17	0	1	13	<u>1.0</u>	0	6					
Z																								
<u>8</u> 9		IGSO-2 IGSO-2	and the second	8.24 4.32	-									ew (3	o site	siep	orting	,						
10		IGSO-2	5.09	3.98		Page generated on Tue Nov 5 12:49:53 2019 (UTC) Data Epoch: 23 seconds prior to page generation, Tue Nov 5 12:49:30 2019 (U																		
11	5	GEO-2	3.83	4.93	4			_	Data E	:pocn:	23 seco	onas pr	ior to p	age ge	neratio	n, Tue	NOV 5	12:49:30	0 201	9 (010)				
12	11	MEO-2	2.65	3.28	4																			
13	12	MEO-2	2.73	4.86	4						GLO In													
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					SVN (?)		(?) (?)		FORI				E <u>CLK</u> ?) (plot,?)	RSS	RAC	SIGMA	Total	Good (plot,?) (Bad	Missing	BCE (plot,?)	AOD (plot,?)	Health (plot,?)	SVN (?)
					and the second second				11. Alt 1				and a second				-		2					Concernation of the local distance of the lo
					719	in the second	M M	<u>0.45</u> 1.55		<u>99.0</u> 99.0		0.22		0.75 2.26	plot plot	0.00	20 21	<u>16</u> <u>16</u>	∠ 1	<u>2</u> 4	<u>0</u>	<u>0.0</u> 0.0	<u>0</u> 0	719 720
					721		M	0.72				0.52			plot	0.00	19	18	0	1	0	0.0	0	720
					723		м	-	-	:		-		-	plot	-	13	0	<u>o</u>	13	0	0.0	0	723
					730		м	2.86	0.71	99.0		0.18			plot	0.00	20	17	0	3	0	0.0	0	730
					731	22	м	0.54	0.46	99.0	0 0.01	0.34	0.24	1.70	plot	0.00	42	39	2	1	<u>0</u>	0.0	<u>0</u>	731
					731	. 22	м	0.54	0.46	<u>99.0</u>	<u>0</u> <u>0.01</u>	0.34	0.24	1.70	plot	0.00	42	<u>39</u>	2	1	<u>o</u>	<u>0.0</u>	<u>0</u>	731

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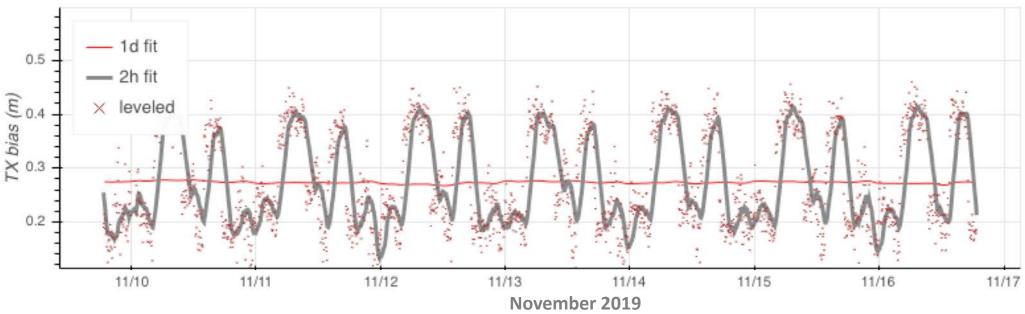


GDGPS monitors inter-signal biases (aka differential code biases) for GPS, BeiDou, and Galileo

JPL's *Tgd* inter-signal bias estimates have been broadcasted by GPS for two decades

Special high rate tracking required for monitoring GPS flex power impact on signal biases

- Onset of regular Flex Power regime in January 2017
- Occasional other Flex Power regimes
- Induced signal biases adversely impact precision orbit determination and positioning applications

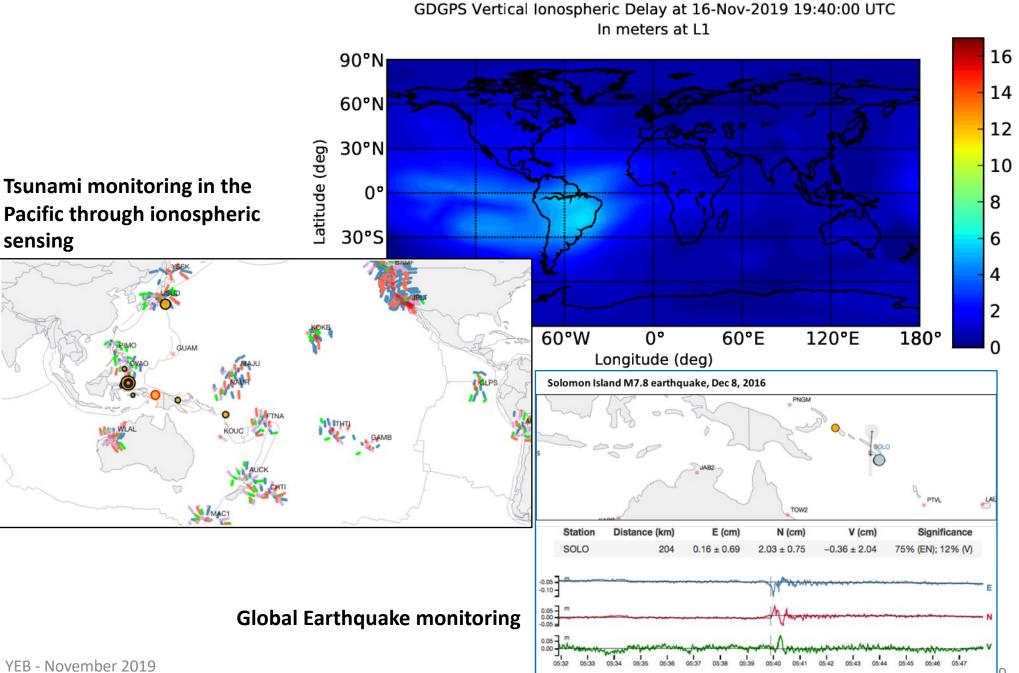


C1C-C1W estimates for GPS72

YEB - November 2019







SOLO



Situational Assessment and Mitigation of Threats to GPS Applications with the GDGPS System

GDGPS Jet Propulsion Caberetory

Threats include:

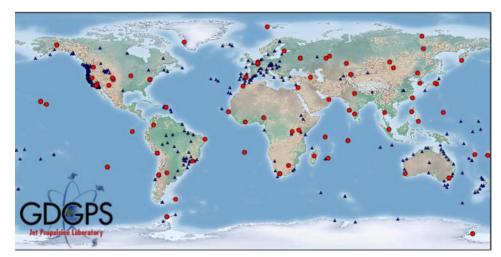
- Integrity failures
- Jamming
- spoofing (of ranging signals and broadcast message)

Approach:

- Use global and regional real-time monitoring networks; exploit the inherent resiliency of globally-tracked GPS
- Authenticate GPS signals based on unspoofable, unjammable GDGPS System
- Apply classical monitoring and big data mining techniques

Beneficiaries:

- Responsible agencies (for example, DHS, DOT)
- Connected users (for example, power grids, communications grids)







Threats	Mitigation Leveraging GDGPS								
Global									
Taking over a GPS satellite	Global integrity monitoring								
Regional (~500 km)									
Spoofing, jamming	Centralized situational assessment using existing GDGPS tracking sites; incorporate hundreds of existing U.S. tracking sites Monitor: SNR, range measurements against established models, patterns (multipath, residuals,), clock jumps, regional comparisons Big data, crowd-sourcing situational assessment								
Point									
Spoofing, jamming	Connected sites get information, validation from a trusted source: Nav messages, ephemeris predictions (already used by millions of cell phone users) Smarter receivers: RAIM, signal analysis,								
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Civilian applications appear as low priority for GPS; Galileo steps up to the challenge

Capability Promoting Precision Civilian Applications	GPS	Galileo
Laser retro reflectors	No (to be reintroduced with SV11)	Yes
Antenna phase calibrations (Earth coverage)	Not for GPS III Some for Block IIR (courtesy LM; inconsistent with science community calibrations) None for Block IIF	Yes (Consistent with science community calibrations – about to be adopted as standard for terrestrial reference frame)
Attitude model	No	Yes
Radiation pressure properties	No	Yes
Signal in space accuracy (URE)	~0.5 m RMS ~0.4 m Median	~0.4 m RMS 0.2 m Median
Mean Age of Data (AOD)	~12 hours	Less than 1 hour
Stable transmit power; stable inter-signal biases	No (Flex Power)	Yes

Going forward, GPS IIIF is considering designs that may further degrade science applications



Why Wait?



Existing global and regional GPS tracking networks, technologies, and operational capabilities enable effective mitigation to some threats to sensitive GPS infrastructure at the U.S. and beyond

- Centralized situational assessment of RFI attacks
- Trusted data services to monitor/replace the broadcast ephemeris
- 'Smarts' can be implemented outside the receiver, and be both distributed and centralized

GDGPS real-time augmentation and situational assessment capabilities extend to all GNSS

Why wait for a more perfect system to enhance infrastructure resiliency?

• Learn from the DoT interminable quest for a perfect civil signal monitoring service

Will GPS become a backup system to Galileo in civilian application?

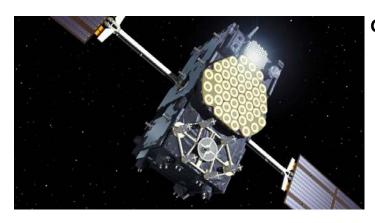
- Has GPS given up on maintaining leadership in civilian and science applications?
- Will geodetic standards, used operationally by GPS (e.g., ITRF) be referenced to Galileo?





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Galileo