



Update on GNSS Performance Monitoring

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the Air Force



Initiated by Aerospace Corporation following the SVN 22 event of November 5, 2002



The JPL GPS performance monitoring service was jointly developed by JPL and Aerospace, with input from the 2SOPS operators

- Funded in recent years by 2SOPS operational budget
- Continuously refined and augmented with additional capabilities
- Use tracking data from 80+ sites in the Global Differential GPS (GDGPS) network
- GDGPS real-time orbit and clock solutions are used as Truth

Monitor key performance metrics of the broadcast ephemeris and the navigation signals

- User range accuracy, due to broadcast or ranging signal
- Correctness of key broadcast parameters
- Satellite observability assessment
- 30 second latency





JPL's Performance Monitor of the GPS Broadcast Navigation Message:

CNAV-L2

Go To: LNAV

19 GPS in view (71 sites reporting)

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Data Epoch: 22 seconds prior to page generation, Fri Jun 23 23:50:00 2017 (UTC)

	GPS Integrity Monitor: Table sorted by SVN without auto-update (Go to version with 30-sec auto-update)																							
				Pe	rforma	nce m	etrics	Or	bit/Clo	ck erre	or met	trics	UTC N	lodel	Link Statistics									
SVN (?)	<u>PRN</u> (<u>?</u>)	Orbit (?)	Block (?)	URE (plot,?)	FORD (plot,?)	URA (plot,?)	URE/URA (plot,?)	UREE (plot,?)	CLK (plot,?)	RSS (plot,?)	RAC (plot,?)	SIGMA (plot,?)	dUTC (plot,?)	dtRef (plot,?)	Total (plot,?)	Good (plot,?)	Bad (plot,?)	Missing (plot,?)	BCE (plot,?)	AOD (plot,?)	 (<u>plot,?</u>)	<u>L2</u> (plot,?)	<u>L5</u> (plot,?)	<mark>SVN</mark> (<u>?</u>)
<u>48</u>	Z	A-4	IIR-M	<u>0.21</u>	<u>1.41</u>	<u>3.44</u>	<u>0.06</u>	<u>0.23</u>	<u>-0.02</u>	<u>0.42</u>	<u>plot</u>	<u>0.03</u>	<u>0.872</u>	<u>17.0</u>	• <u>41</u>	<u>12</u>	<u>29</u>	<u>0</u>	<u>13</u>	<u>17.0</u>	<u>0</u>	<u>0</u>	1	• <u>48</u>
<u>50</u>	<u>5</u>	E-3	IIR-M	<u>0.47</u>	<u>1.15</u>	<u>2.48</u>	<u>0.19</u>	<u>0.28</u>	<u>-0.25</u>	<u>1.64</u>	<u>plot</u>	<u>0.03</u>	<u>0.916</u>	<u>12.5</u>	<u>26</u>	<u>24</u>	<u>0</u>	2	<u>14</u>	<u>12.5</u>	• <u>0</u>	<u>0</u>	1	<u>50</u>
<u>52</u>	<u>31</u>	A-2	IIR-M	<u>0.52</u>	<u>3.18</u>	<u>2.75</u>	<u>0.19</u>	<u>0.17</u>	<u>-0.67</u>	<u>0.57</u>	plot	<u>0.03</u>	<u>0.905</u>	<u>14.2</u>	<u>56</u>	<u>27</u>	<u>29</u>	<u>0</u>	<u>19</u>	<u>14.2</u>	<u>0</u>	<u>0</u>	1	<u>52</u>
<u>53</u>	<u>17</u>	C-4	IIR-M	<u>1.20</u>	<u>1.93</u>	<u>2.27</u>	<u>0.53</u>	<u>0.41</u>	<u>-1.47</u>	<u>2.02</u>	plot	<u>0.03</u>	<u>0.912</u>	<u>11.2</u>	<u>22</u>	<u>21</u>	<u>0</u>	1	<u>17</u>	<u>11.2</u>	<u>0</u>	<u>0</u>	1	<u>53</u>
<u>55</u>	<u>15</u>	F-2	IIR-M	<u>0.39</u>	<u>0.95</u>	<u>2.38</u>	<u>0.16</u>	<u>0.17</u>	-0.25	<u>0.97</u>	<u>plot</u>	<u>0.04</u>	<u>0.912</u>	<u>11.2</u>	<u>41</u>	<u>12</u>	<u>29</u>	<u>0</u>	<u>8</u>	<u>11.2</u>	<u>0</u>	<u>0</u>	1	<u>55</u>
57	<u>29</u>	C-1	IIR-M	<u>0.78</u>	<u>1.96</u>	<u>2.48</u>	<u>0.31</u>	<u>0.21</u>	-0.68	<u>1.38</u>	<u>plot</u>	<u>0.03</u>	<u>0.916</u>	<u>12.5</u>	<u>20</u>	<u>20</u>	<u>0</u>	<u>0</u>	<u>16</u>	<u>12.5</u>	<u>0</u>	<u>0</u>	1	<u>57</u>
<u>58</u>	<u>12</u>	B-4	IIR-M	<u>0.21</u>	<u>0.97</u>	<u>2.71</u>	<u>0.08</u>	<u>0.15</u>	<u>0.36</u>	<u>0.26</u>	<u>plot</u>	<u>0.03</u>	<u>0.872</u>	<u>17.0</u>	25	<u>25</u>	<u>0</u>	<u>0</u>	<u>14</u>	<u>17.0</u>	<u>0</u>	<u>0</u>	1	<u>58</u>
<u>62</u>	<u>25</u>	B-2	IIF	<u>0.12</u>	<u>1.39</u>	2.20	<u>0.06</u>	<u>0.28</u>	<u>0.36</u>	<u>0.64</u>	<u>plot</u>	<u>0.03</u>	<u>0.962</u>	<u>7.2</u>	<u>28</u>	<u>28</u>	<u>0</u>	<u>0</u>	<u>20</u>	7.2	<u>0</u>	<u>0</u>	1	<u>62</u>
<u>63</u>	1	D-2	IIF	<u>0.20</u>	<u>1.30</u>	<u>1.62</u>	<u>0.12</u>	<u>0.15</u>	<u>0.05</u>	<u>0.67</u>	plot	<u>0.03</u>	<u>0.803</u>	<u>4.5</u>	<u>79</u>	<u>21</u>	<u>58</u>	<u>0</u>	<u>14</u>	<u>4.5</u>	<u>0</u>	<u>0</u>	1	<u>63</u>
<u>64</u>	<u>30</u>	A-3	IIF	<u>0.21</u>	<u>0.81</u>	2.29	<u>0.09</u>	<u>0.25</u>	<u>-0.33</u>	<u>1.11</u>	plot	<u>0.03</u>	<u>0.928</u>	<u>8.5</u>	<u>47</u>	<u>17</u>	<u>29</u>	1	<u>10</u>	<u>8.5</u>	<u>0</u>	<u>0</u>	1	<u>64</u>
<u>65</u>	<u>24</u>	A-1	IIF	<u>0.34</u>	<u>1.50</u>	<u>2.31</u>	<u>0.15</u>	<u>0.45</u>	<u>0.11</u>	<u>0.68</u>	plot	<u>0.03</u>	<u>0.826</u>	<u>3.2</u>	<u>13</u>	<u>12</u>	<u>0</u>	1	Z	<u>3.2</u>	<u>0</u>	<u>0</u>	1	<u>65</u>
<u>66</u>	<u>27</u>	C-2	IIF	<u>0.30</u>	<u>3.04</u>	<u>1.64</u>	<u>0.18</u>	<u>0.06</u>	<u>0.26</u>	<u>0.38</u>	plot	<u>0.03</u>	<u>0.822</u>	<u>4.7</u>	73	<u>14</u>	<u>58</u>	1	<u>10</u>	<u>4.7</u>	<u>0</u>	<u>0</u>	1	<u>66</u>
<u>67</u>	<u>6</u>	D-4	IIF	<u>0.42</u>	<u>0.71</u>	<u>2.20</u>	<u>0.19</u>	<u>0.19</u>	<u>-0.29</u>	<u>1.19</u>	plot	<u>0.03</u>	<u>0.962</u>	<u>7.2</u>	<u>31</u>	<u>31</u>	<u>0</u>	<u>0</u>	<u>18</u>	7.2	<u>0</u>	<u>0</u>	1	<u>67</u>
<u>68</u>	9	F-3	IIF	<u>0.14</u>	<u>1.03</u>	<u>2.20</u>	<u>0.06</u>	<u>0.13</u>	<u>0.00</u>	<u>0.64</u>	plot	<u>0.03</u>	<u>0.962</u>	<u>7.2</u>	47	<u>17</u>	27	3	<u>17</u>	7.2	<u>0</u>	<u>0</u>	1	<u>68</u>
<u>69</u>	3	E-1	IIF	<u>0.28</u>	<u>1.65</u>	<u>1.57</u>	<u>0.18</u>	<u>0.12</u>	<u>0.18</u>	<u>0.61</u>	plot	<u>0.03</u>	<u>0.805</u>	<u>3.7</u>	<u>53</u>	<u>24</u>	<u>29</u>	<u>0</u>	<u>17</u>	<u>3.7</u>	<u>0</u>	<u>0</u>	1	<u>69</u>
70	<u>32</u>	F-1	IIF	<u>0.26</u>	<u>3.58</u>	<u>4.23</u>	<u>0.06</u>	<u>0.20</u>	<u>-0.09</u>	<u>1.26</u>	plot	<u>0.03</u>	<u>0.944</u>	<u>24.0</u>	<u>46</u>	<u>17</u>	<u>29</u>	<u>0</u>	<u>16</u>	24.0	<u>0</u>	<u>0</u>	1	<u>70</u>
71	<u>26</u>	B-1	IIF	<u>0.36</u>	<u>3.67</u>	<u>2.40</u>	<u>0.15</u>	<u>0.16</u>	<u>0.20</u>	<u>0.31</u>	plot	<u>0.04</u>	<u>0.953</u>	<u>10.0</u>	<u>49</u>	<u>20</u>	<u>29</u>	<u>0</u>	<u>18</u>	<u>10.0</u>	<u>0</u>	<u>0</u>	1	71
72	<u>8</u>	C-3	IIF	<u>0.71</u>	<u>2.18</u>	2.46	<u>0.29</u>	<u>0.12</u>	<u>0.60</u>	<u>0.39</u>	plot	<u>0.03</u>	<u>0.928</u>	<u>8.5</u>	<u>44</u>	<u>15</u>	<u>29</u>	<u>0</u>	<u>10</u>	<u>8.5</u>	<u>0</u>	<u>0</u>	1	72
<u>73</u>	<u>10</u>	E-2	IIF	<u>0.18</u>	<u>2.71</u>	<u>4.23</u>	<u>0.04</u>	<u>0.13</u>	<u>-0.07</u>	<u>0.84</u>	plot	<u>0.03</u>	<u>0.944</u>	<u>24.0</u>	<u>42</u>	<u>13</u>	<u>29</u>	<u>0</u>	<u>10</u>	<u>24.0</u>	<u>0</u>	<u>0</u>	1	<u>73</u>
SVN	PRN	Orbit	Block	URE	FORD	URA	URE/URA	UREE	CLK	RSS	RAC	SIGMA	dUTC	dtRef	Total	Good	Bad	Missing	BCE	AOD	L1	<u>L2</u>	<u>L5</u>	SVN

Recently-added capabilities:

- CNAV monitoring on L2 and L5
- UTC model (after the Jan 2016 event) YEB - June 2017
- Differential Code Biases monitoring
- GNSS time transfer parameters (in 2018)

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Snapshot of the GDGPS CNAV Monitoring Web Page (contd.) GDGPS









Leveraging JPL's ionospheric expertise and dense global network

YEB - June 2017





JPL's Tgd estimates are being broadcast by GPS; Updated quarterly and on change



6



The Foundation: Extremely Redundant Global Real-Time Tracking Network



80+ global tracking sites deployed, controlled, operated, and maintained by JPL's GDGPS System

- Hardware and software fully owned and controlled by JPL
- Decades of site stability, quality, and continuity
- **25-fold** observation redundancy, on average, enable strong majority voting schemes

Hundreds of contributed sites operated by a variety of partners, U.S. and foreign agencies (e.g., NSF, BKG, GA) provide additional level of redundancy and density of coverage







JPL already monitors and reports all the key navigation metrics of the GPS civil signals

JPL already possesses all the data needed to verify 90% of the Civil Monitoring Performance Specifications (CMPS)

JPL proposed to monitor 98% of the CMPS within a year

- Leveraging the significant NASA and USAF investment in the GDGPS System
- PNT AB recommended using the cost-effective GDGPS system for CSM (Parkinson, 2013)
- The proposal was analyzed by the FAA 2014 CSM Trade Study Team and found attractive

recommendations are:

- 1. Submit a request for proposal to Raytheon for buying P1-P2 with an option for P3 requirements
- 2. Submit a request for proposal to NASA JPL for buying and maintaining the Non-OCX element with SQM monitoring
- 3. The civil community should engage with Air Force Space Command to establish operational procedures for GPS control of signals used by the civil community that utilize increasing amounts of Non-OCX monitoring information over time.

Refined proposal (worked with FAA) submitted to FAA in October 2015. Then silence.



GPS Civil Signal Monitoring Trade Study Report DOT-VNTSC-FAA-14-06 March 7, 2014

Real-Time GNSS Performance Monitoring Available now



GDGPS is monitoring the civil signals from GLONASS, BeiDou, and Galileo. Soon, QZSS

- IRNSS monitoring is being assessed
- 100% redundant global coverage

Full RTGX-based development server processing GLO broadcast

24 GLO in view (59 sites reporting)

Page generated on Fri Jun 23 19:51:48 2017 (UTC) Data Epoch: 18 seconds prior to page generation, Fri Jun 23 19:51:30 2017 (UTC)

Full RTGX-based development server processing BDS broadcast																																	
14 BDS in view (42 sites reporting)												GLO Integrity Monitor: Table sorted by SVN without auto-update (Go to version with 30-sec auto-update)																					
Page generated on Fri Jun 23 20:08:18 2017 (UTC)														Performance metrics				Or	bit/Clo	ck erre	or met	rics	Link Statistics										
	D	ata Epo	och: 1	8 second	ls prio	r to pa	je gene	eratior	n, Fri Ju	n 23 2	0:08:00) 2017 (l	SVN (?)	<u>PRN</u> (<u>?</u>)	Orbit (?)	Block (?)	URE (plot,?)	FORD (plot,?)	URA (plot,?)	URE/URA (plot,?)	UREE (plot,?)	CLK (plot,?)	RSS (plot,?)	RAC (plot,?)	SIGMA (plot,?)	Total (plot,?)	Good (plot,?)	Bad (plot,?)	Missing (plot,?)	BCE (plot,?)	• <u>AOD</u> (<u>plot,?</u>)	Health (plot,?)	SVN (<u>?</u>)
			BD	S Inte	grity	y Mor	itor:	Tab	le sor	ted b	y SV	N	715	<u>14</u>	м		<u>4.21</u>	<u>3.47</u>	<u>99.00</u>	<u>0.04</u>	<u>0.58</u>	<u>4.72</u>	<u>1.96</u>	plot	<u>0.03</u>	<u>10</u>	<u>9</u>	1	Q	<u>9</u>	<u>0.0</u>	<u>0</u>	<u>715</u>
without auto-update (Go to version with 30-sec auto-update)											716	<u>15</u>	м	۰ ۱	<u>1.41</u>	2.30	<u>99.00</u>	<u>0.01</u>	<u>0.62</u>	1.29	4.44	plot	<u>0.03</u>	<u>15</u>	<u>13</u>	2	<u>0</u>	<u>18</u>	<u>0.0</u>	<u>0</u>	<u>716</u>		
	Perf	Performance metrics				Orbit/Clock error metrics			rics	Link Sta			717	<u>10</u>	м	•	=	2	±	-	° =	=	–	plot	=	• <u>17</u>	<u>15</u>	2	<u>0</u>	<u>25</u>	<u>0.0</u>	<u>0</u>	- <u>717</u>
SVN PRN Orbit Block	URE	FORD	URA	URE/URA	UREE	<u>CLK</u>	RSS	RAC	SIGMA	Total	Good	Bad M	719	<u>20</u>	М	۰ ۱	<u>1.46</u>	<u>1.65</u>	<u>99.00</u>	<u>0.01</u>	<u>0.86</u>	<u>0.67</u>	<u>3.89</u>	plot	<u>0.03</u>	<u>10</u>	<u>8</u>	2	<u>0</u>	<u>10</u>	<u>0.0</u>	<u>0</u>	<u>719</u>
	<u>plot,?</u>) ((<u>plot,?</u>) (plot,?)	(<u>plot,?</u>)	(<u>plot,?</u>)) (<u>plot,?</u>)	(<u>plot,?</u>)	(plot,?)	(<u>plot,?</u>)	(plot,?)	(<u>plot,?</u>)	(<u>plot,?</u>) (720	<u>19</u>	м	۰ ۱	<u>1.32</u>	<u>1.57</u>	<u>99.00</u>	<u>0.01</u>	• <u>1.36</u>	<u>-0.10</u>	<u>7.86</u>	plot	<u>0.03</u>	<u>16</u>	<u>12</u>	4	<u>0</u>	<u>21</u>	<u>0.0</u>	<u>0</u>	<u>720</u>
<u>101</u> <u>1</u> GEO-1	-	-	=		=	-	-	plot	-	29	21	3	721	<u>13</u>	м	•	<u>0.41</u>	<u>3.35</u>	<u>99.00</u>	<u>0.00</u>	<u>0.78</u>	<u>-0.41</u>	<u>1.74</u>	plot	<u>0.03</u>	<u>12</u>	<u>11</u>	<u>0</u>	1	11	<u>0.0</u>	<u>0</u>	<u>721</u>
103 3 GEO-1	2.69	2.87	4.00	0.67	0.82	-2.41	5.79	plot	0.03	29	20	2	723	<u>12</u>	М	۰ ۱	=	÷	=	=	° =	=	–	<u>plot</u>	=	<u>15</u>	1	0	<u>14</u>	<u>13</u>	<u>0.0</u>	<u>0</u>	<u>723</u>
105 5 GEO-1	1.41	2.42	4.00	0.35	0.78	1.75	4.45	plot	0.03	19	13	2	730	1	м	۰ ۱	2.45	<u>2.64</u>	<u>99.00</u>	<u>0.02</u>	<u>0.11</u>	<u>2.36</u>	<u>0.51</u>	plot	<u>0.02</u>	<u>23</u>	<u>20</u>	3	<u>0</u>	<u>22</u>	<u>0.0</u>	<u>0</u>	<u>730</u>
106 2 GEO-1	0.39	2.01	4.00	0.10	0.39	-0.30	2.60	plot	0.03	26	15	3	731	22	м	۰ ۱	=	÷	-	=	° _	-	-	plot	-	17	<u>15</u>	1	1	<u>13</u>	<u>0.0</u>	<u>0</u>	<u>731</u>
201 <u>6</u> IGSO-1	2.00	3.09	<u>4.00</u>	<u>0.50</u>	<u>0.17</u>	<u>-1.95</u>	<u>1.18</u>	plot	0.03	<u>25</u>	<u>17</u>	1	732	23	M	۰ ۱	1.34	<u>3.71</u>	<u>99.00</u>	<u>0.01</u>	<u>0.34</u>	1.13	2.06	<u>plot</u>	0.03	<u>13</u>	<u>10</u>	1	2	<u>16</u>	<u>0.0</u>	0	<u>732</u>
202 7 IGSO-1	<u>4.16</u>	5.98	4.00	<u>1.04</u>	2.52	<u>-6.68</u>	2.64	plot	<u>0.03</u>	<u>26</u>	<u>19</u>	2	733	<u>6</u>	м	۰ ۱	<u>1.21</u>	<u>3.01</u>	<u>99.00</u>	<u>0.01</u>	<u>0.75</u>	<u>0.47</u>	1.69	plot	<u>0.03</u>	<u>14</u>	<u>10</u>	1	3	<u>15</u>	<u>0.0</u>	<u>0</u>	<u>733</u>
203 <u>8</u> IGSO-1	<u>2.20</u>	<u>3.98</u>	<u>4.00</u>	<u>0.55</u>	<u>3.45</u>	<u>-5.63</u>	<u>3.75</u>	plot	<u>0.04</u>	<u>23</u>	<u>15</u>	<u>3</u>	734	5	м	۰ ۱	3.33	<u>2.64</u>	<u>99.00</u>	<u>0.03</u>	<u>0.60</u>	2.83	2.65	plot	<u>0.03</u>	11	2	1	1	<u>8</u>	<u>0.0</u>	<u>0</u>	<u>734</u>
204 9 IGSO-1	2.04	<u>1.81</u>	4.00	<u>0.51</u>	<u>0.86</u>	<u>1.19</u>	<u>1.54</u>	plot	<u>0.03</u>	<u>22</u>	<u>18</u>	1	735	<u>24</u>	м	۰ ۱	<u>0.11</u>	1.78	<u>99.00</u>	<u>0.00</u>	<u>0.54</u>	<u>-0.45</u>	<u>0.70</u>	plot	<u>0.02</u>	23	<u>19</u>	1	3	<u>15</u>	<u>0.0</u>	<u>0</u>	<u>735</u>
205 10 IGSO-1	3.53	3.83	4.00	0.88	3.46	0.08	3.49	plot	0.03	26	21	3	736	<u>16</u>	м	۰ ۱	<u>0.41</u>	<u>3.37</u>	<u>99.00</u>	<u>0.00</u>	<u>0.46</u>	<u>-0.78</u>	1.45	plot	<u>0.03</u>	17	14	2	1	<u>24</u>	<u>0.0</u>	<u>0</u>	<u>736</u>
208 13 1050-1	3 45	2.57	4.00	0.86	1.36	2 12	2.58	plot	0.04	24	12	2	742	4	м	۵ ۱	=	÷	-		° <u>-</u>	-	÷	plot	-	2	8	0	1	8	<u>0.0</u>	<u>0</u>	<u>742</u>
304 12 MEO-1	3.49	3.08	4.00	0.87	0.99	2.60	3.71	plot	0.04	14	11	2	743	8	M	۰ ۱	5.01	1.97	<u>99.00</u>	0.05	0.25	-5.20	1.16	plot	0.02	<u>18</u>	15	2	1	24	<u>0.0</u>	<u>0</u>	<u>743</u>
306 14 MEO-1	1.85	1.84	4.00	0.46	1.53	0.32	1.57	plot	0.03	28	21	3	744	3	M	۲ ۲	4.83	3.95	99.00	0.05	0.84	-5.33	4.63	plot	0.03	<u>16</u>	13	2	1	16	0.0	<u>0</u>	744
SVN PRN Orbit Block	URE	FORD	URA	URE/URA	UREE	CLK	RSS	RAC	SIGMA	Total	Good	Bad M	745	4	M	۵ ۱	1.38	2.26	99.00	0.01	0.33	-1.70	0.56	piot	0.03	18	15	2	0	18	0.0	<u>u</u>	<u>745</u>
					_								<u>/4/</u>	2	M	۲ ۱	4.31	1.85	99.00	0.04	0.80	3.52	1.44	plot	0.02	22	13	1	8	<u>19</u>	0.0	0	<u>/4/</u>
													802	2	K1	۲ ۲	2.48	3.65	99.00	0.03	0.76	-3.04	3.42	piot	0.03	23	10	4	0	29	<u>0.0</u>	<u>v</u>	802
													851	1/	P1	ſ.	2.49	2.45	99.00	0.03	0.76	-3.08	3.11	piot	0.02	24	22	∠ 1	0	21	0.0	<u>v</u>	851
													853	10	P1 M	ŝ	2.00	2.32	99.00	0.01	0.56	-0.05	0.96	piot	0.03	15	14	1	0	18	0.0	2	853
													054	18	11	^c	2.90	2.88	99.00	0.03	0.52	2.38	0.72	piot	0.02	20	<u>22</u>	-	0	<u> 20</u>	0.0	<u>v</u>	054

High accuracy real time orbit and clock solutions provide some benefits relative to GPS-only in certain applications

• e.g. Earthquake monitoring:





GDGPS Real-Time Natural Hazard Monitoring





Real-Time detection of tsunami ionospheric disturbances with GNSS ground tracking (Savastano et al., Nature, 2017)







08:37:00 GPS time







Existing and proven GDGPS tracking networks, technologies, and operational capabilities can provide effective and low cost GPS civil signal monitoring

JPL's GDGPS System already tracks and monitors GLONASS, BeiDou, and Galileo on a global scale

- Can be used to alleviate concerns in the U.S. about incorporating GNSS signals into certain regulated services, such as E-911 geolocation
- The system is already being used commercially to provide Assisted GNSS services to millions of mobile users





GNSS Monitoring

Providing mission-critical, real-time services, 24/7, since 2000 Full GNSS capabilities: GPS, GLONASS, BeiDou, Galileo



Prototype system and testbed for Next Generation GPS Control Segment (OCX)

Time-critical environmental monitoring services

Repeat path interferometry with UAV-SAR



Earthquake monitoring GNSS navigation data for and tsunami prediction





Radio Occultations



Space weather monitoring

