



Activities on GNSS System Time Interoperability at NTSC

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54th Meeting of The Civil GPS Service Interface Committee at ION GNSS+2014 Conference September, 2014



Guideline

1. Introduction

2. Relationship between BDT and UTC(NTSC)

3.GNSS Time Offset Monitoring and Forecasting

4. GPST-GLONASST Application for Combination Positioning



1. Introduction

- In order to implement the traceability of BDT to UTC by using UTC(NTSC), time comparison links between BDS and NTSC including TW, GPSCV and BDSCV have been set up gradually since 2010.
- GPS, Galileo and BDS plan to broadcast the system time offset with other systems in their navigation information in order to support GNSS system time interoperability.
- BDS also promotes the system time interoperability vigorously.
 - In BSD ICD, the interfaces have been defined for system time offset forecast parameters with GPS, GLONASS, Galileo and so on.
- National Time Service Center has built a system time offset monitoring and forecast system for supporting the system time interoperability.



Timekeeping of UTC(NTSC)

Clock Assembly



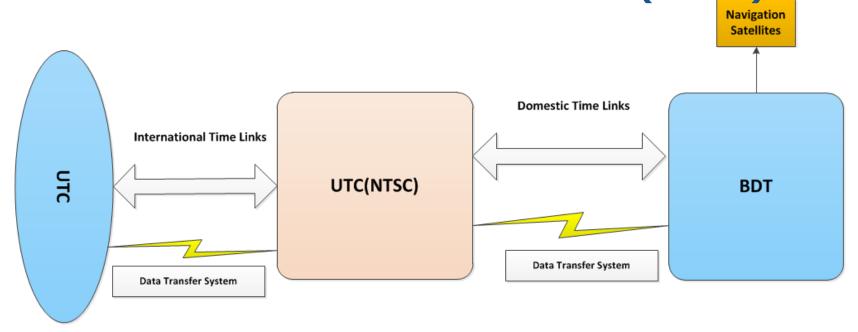
34 Cesium + 4 maser







BDT is traced to UTC via UTC(NTSC)

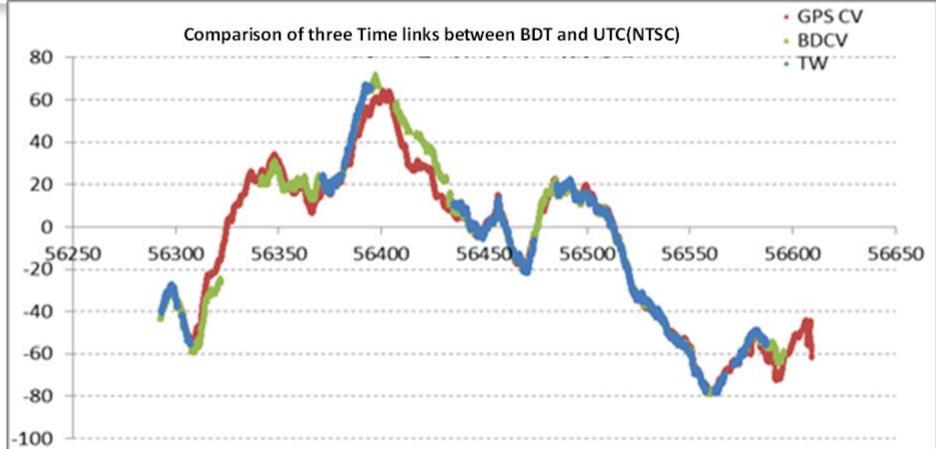


- International Time Links : TW Ku-band, GPS PPP, GPS
 CV
- Domestic Time Links: TW C-band, BDS CV, GPS CV

Performance of the Time Links (Uncertainty)

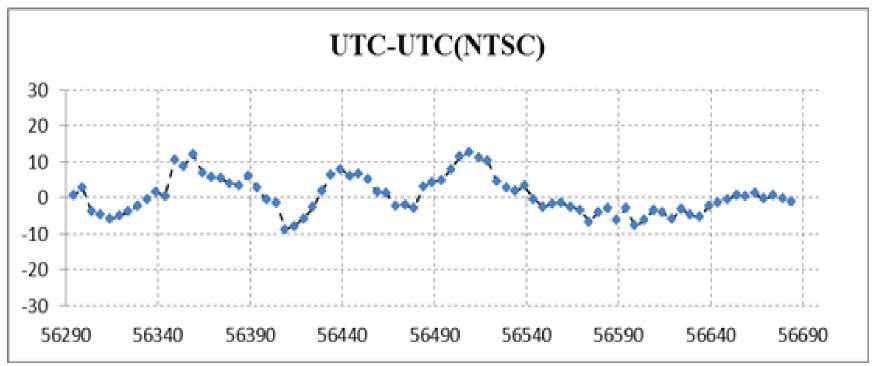
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    ➤ International :
        TWSTFT: 0.5ns (A)
        GPS PPP: 0.3ns (A)
        GPS CV: 5ns (A+B)
    ➤ Domestic :
        TWSTFT: 0.4ns (A)
        BDS/GPS CV: 5ns (A+B)
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 Comparison of different time links between BDT and UTC(NTSC) from November 2012 to December 2013 by TWSTFT C-band, GPS CV and BDS CV shows good consistency.

Data sources : December 29th,2013~February 2th,2014
 (MJD=56290~56690)

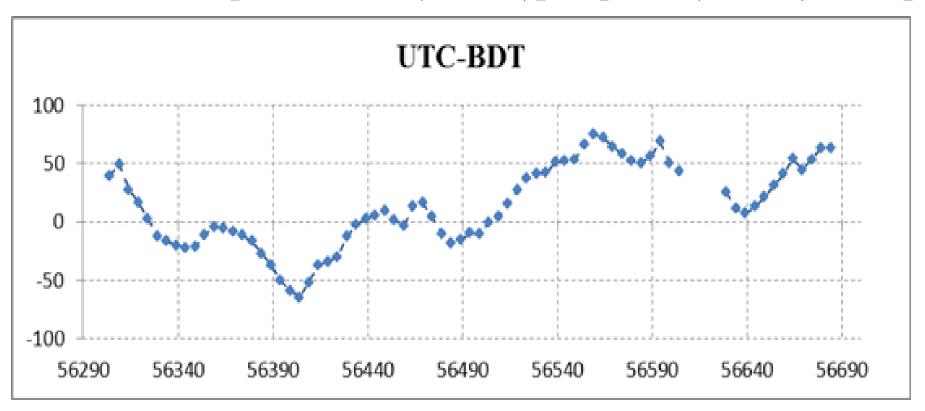


• UTC-UTC(NTSC) is kept within ± 10 ns

We.

2. Relationship between BDT and UTC(NTSC)

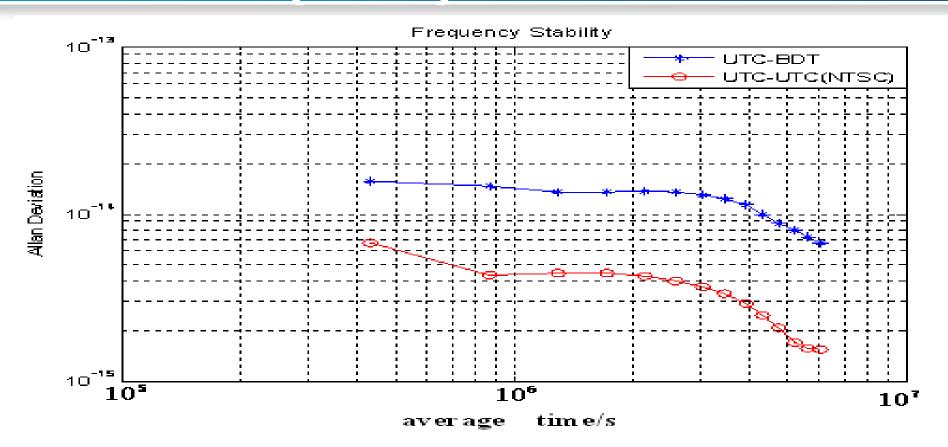
UTC-BDT = [UTC-UTC(NTSC)] + [UTC(NTSC)-BDT]



From above figure, we can see UTC-BDT is kept within 100ns.

W_e

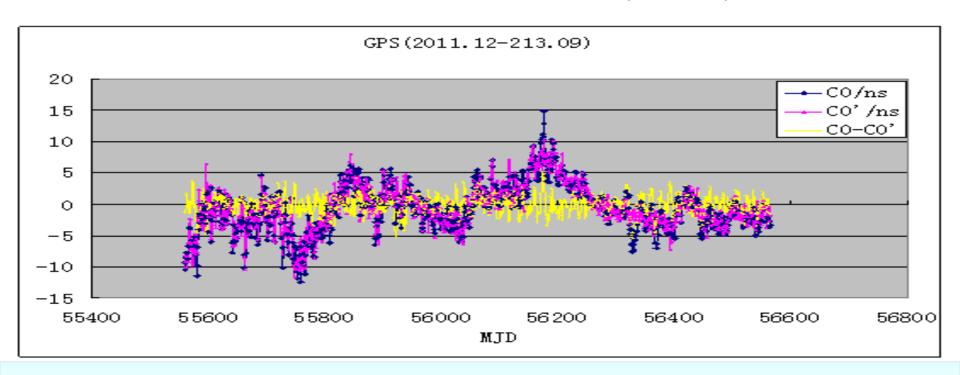
2. Relationship between BDT and UTC(NTSC)



- Frequency stability of BDT: 5.8e-14($\tau = 5 \text{ days}$)
- Frequency stability of UTC(NTSC): 6.7e-15 ($\tau = 5 \text{ days}$)

Compare with GPST traceability

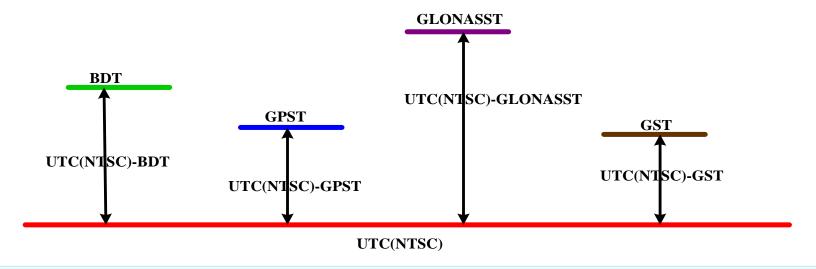
[UTC-GPS time] = -16 s + C0, $[UTC-UTC(USNO)_GPS] = C0$



C0 is in accordance with C0'. The C0- C0' offset is within ±5ns. It can verify the traceability of GPST to its time base.

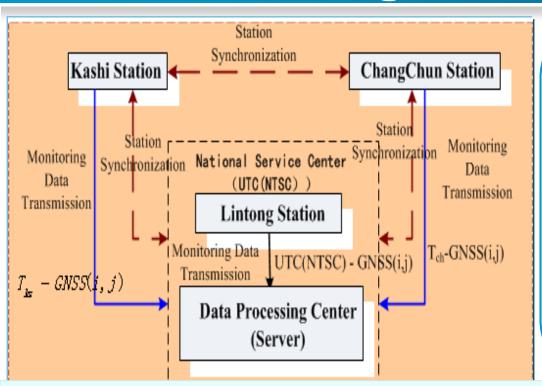


Fundamental of GNSS system time offset monitoring



- UTC (NTSC) is taken as medium time scale. Then system time offsets between GNSS time and UTC(NTSC) are monitored by GNSS SIS: UTC(NTSC)-BDT/GPST/GLONASST/GST
- In terms of each two monitored values, system time offset between two GNSSs can be derived, such as BDT-GPST
- Then system time offset prediction can be calculated.





Three stations

- Equipment
 - Cesium clock
 - ✓ Multi-GNSS Receiver
 - √ Time Interval Counter
 - Pulse and Frequency distribution unit
- Station monitoring software

One Data Processing Center

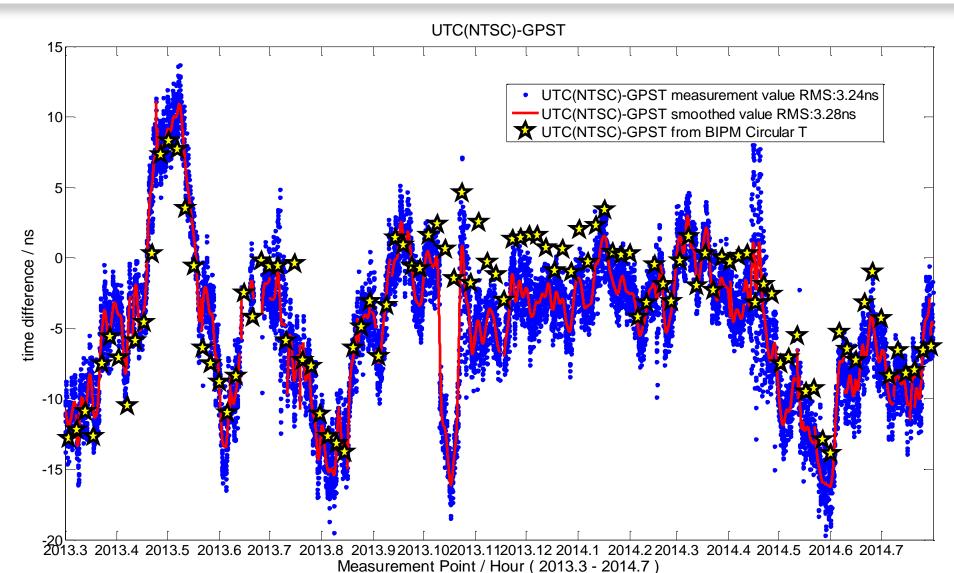
- ✓ Server
- Data integrated processing software
- Three stations, Lintong, Changchun and Kashi, have been set up and a multi-GNSS receiver is installed at each station
- Station time synchronization and remote data transmission are done in real time
- Receiver and antenna calibration are rigorously conducted



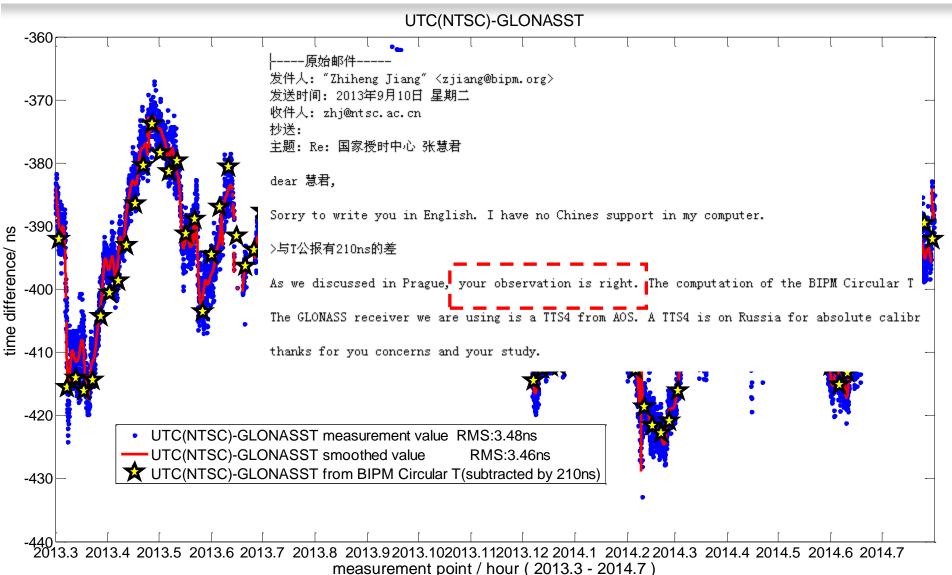
 The results of GNSS system time offset monitoring and forecasting are issued every day through Internet in the form of FTP file

ftp://210.72.145.14:21

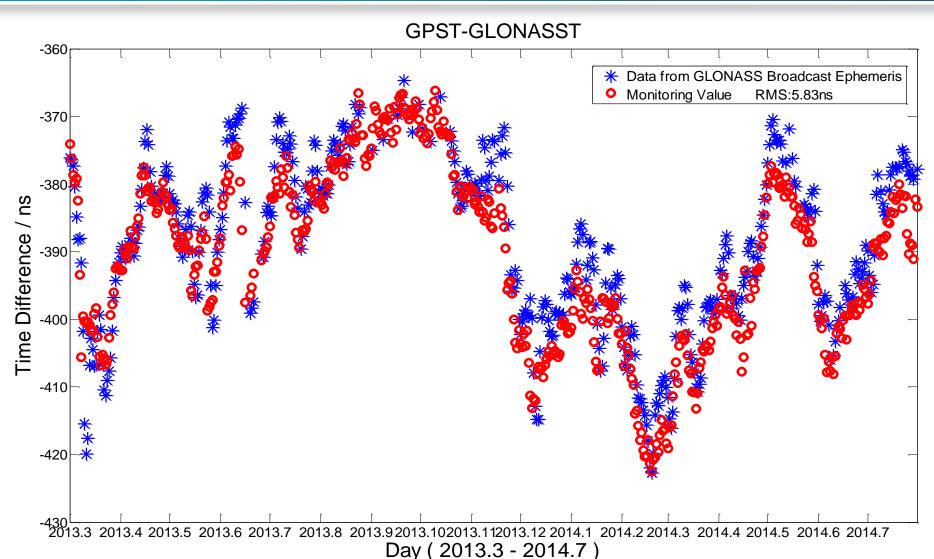




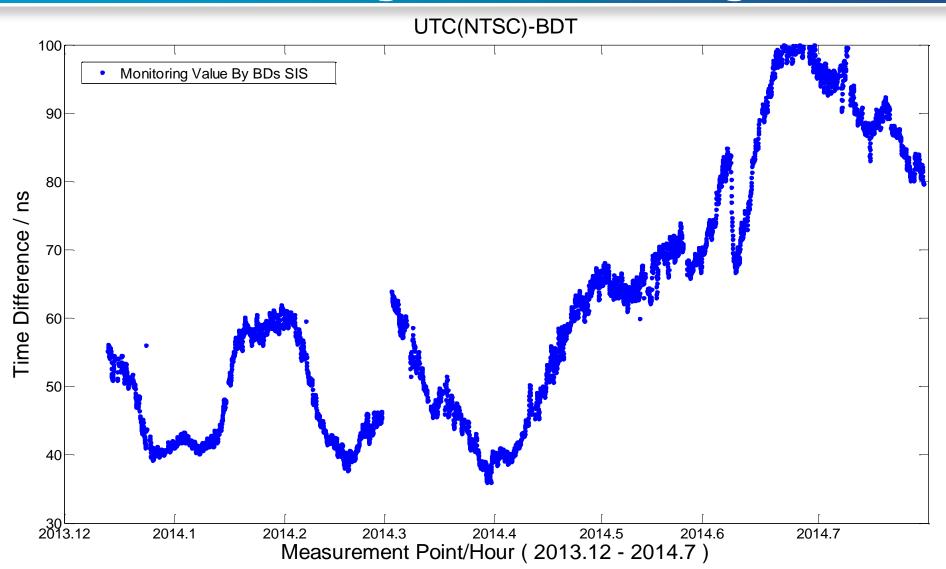














4. GPST-GLONASST - Applications for Combination Positioning

- 4.1 the effect of GPST-GLONASST on combination positioning
- 4.2 Forecasting outcomes of GPST-GLONASST are applied to assist multi-GNSS positioning



5.6

PDOP

11.0

4.1 the Effect of GPST-GLONASST on

Combination Positioning						
	GPS	GLONASS	GPS/GLONASS (user lever solution)	GPS/GLONASS (GPST-GLONASST is utilized)		
10° cutoff						
GDOP	2.1	2.4	1.6	1.5		
PDOP	1.8	1.9	1.4	1.3		
20° cutoff						
GDOP	4.0	4.7	2.4	2.2		
PDOP	3.6	3.8	2.2	2.0		
30° cutoff						
GDOP	6.0	11.8	6.0	4.4		

5.3

4.0



4.1 the Effect of GPST-GLONASST on Combination Positioning

	GPS	GLONASS	GPS/GLONASS (user lever solution)	GPS/GLONASS GPST-GLONASST is utilized)	
10° cutoff RMS(m)					
X	2.73	3.43	2.32	2.25	
У	2.75	3.68	2.41	2.34	
z	2.68	3.15	2.24	2.16	
20 ⁰ cutoff RMS(m)					
X	4.54	5.42	3.04	2.56	
У	5.62	7.01	5.11	3.42	
z	6.33	8.26	5.25	4.47	
30° cutoff RMS(m)					
X	7.53	9.94	4.09	3.17	
У	11.77	15.76	7.29	5.21	
		1000			



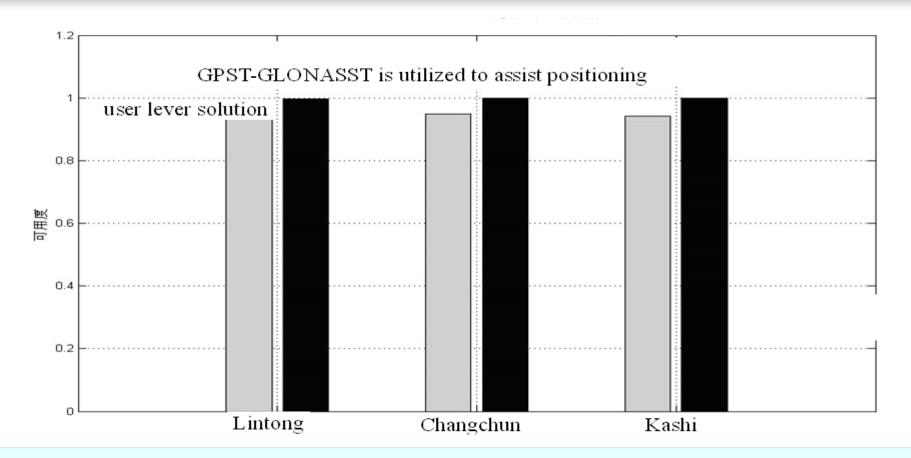
4.2 Forecasting Outcomes of GPST-GLONASST Are Applied to Assist Multi-GNSS Positioning

	PDOP distribution in one day (percentage)				
	PDOP≤6	6 <pdop<39< th=""><th>PDOP≥39</th><th>PDOP minimum</th><th>PDOP maximum</th></pdop<39<>	PDOP≥39	PDOP minimum	PDOP maximum
Lintong	93.5%	6.3%	0.2%	2.07	45.7
Changchun	94.8%	5.2%	0	2.05	17.32
Kashi	94.2%	5.8%	0	2.02	11.74

GPST-GIONASST forecast is adopted to assist combined positioning when PDOP is greater than 6 and less than 39,in order to meet positioning requirement.



4.2 Forecasting of GPST-GLONASST Is Applied to Assist Multi-GNSS Positioning



When using assist positioning, availability can be improved to nearly 100%



4.2 Forecasting of GPST-GLONASST Is Applied to Assist Multi-GNSS Positioning

	GPST-GLONASST User lever solution	GPST-GLONASST (Broadcasted by GLONASS)	GPST-GLONASST (forecasted outcomes)		
Lintong station					
x	3.47	2.76	2.25		
У	9.36	5.46	4.83		
z	17.24	9.53	9.39		
x	5.81	4.23	3.86		
У	15.32	5.42	4.77		
Z	19.7	7.39	6.83		
X	2.95	2.58	2.49		
У	12.66	7.99	7.63		
Z	9.43	5.84	5.57		

