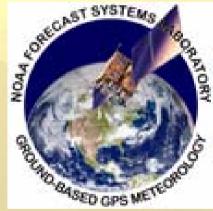


High Accuracy Jationwide Differential obal Positioning System (HA-NDGPS)







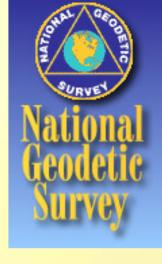
US Army Corps

of Engineers®

Jim Arnold September, 2009



Federal Highway Administration



Problem Statement & Program Objective

Problem Statement: Submeter resolution of vehicle position Needed for many advanced vehicle safety concepts.

Program Objective: Assess the implementation feasibility for improving the accuracy of the NDGPS service, using existing infrastructure, to meet the requirements of additional applications without decreasing availability and integrity and still meeting the needs of existing users.

Perspective on Accuracy Horizontal, Dynamic, 95%

HA-NDGPS(Dynamic) (.1 Meters) HA-NDGPS(Static) (.01 Meters)

> NDGPS (1-2 meters)

> > GPS (13 meters)

Program Phase

Phase I – Make the System Work

- Develop Modulator and Data Link Receivers
- ✓ Interface System Modules
- Broadcast Characterization and Optimization
- ✓ Single Site Concept Demonstration (Hagerstown, MD)

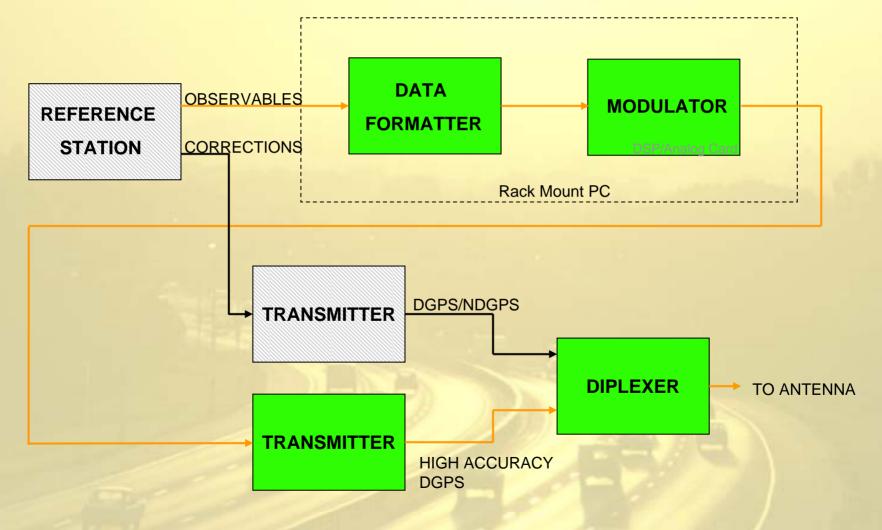
Phase II – Refine the Approach

- ✓ Pre-Broadcast Integrity Algorithm
- Multiple Site/Baseline Concept Demonstration (Hawk Run, PA)
- ✓ Iono/Tropo Prediction
- ✓ Application Development

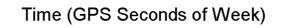
Phase III – Develop the Applications

- ✓ Define/Document site changes
- ✓ Develop Test Plans

Broadcast Site Configuration Phase I



Long Range Single Baseline Test Phase I **Tangier Island HA-NDGPS Experiment** (250 km). Comparison of approximate "truth" geodetic coordinates of mail boat With the real-time solution based upon +σ. the HA-NDGPS broadcast. Results are +σ_ +σ.. 0.5 roughly 10-20 centimeters as expected North Errors at this great range. East Errors 0.4 Height Errors -σ_N 0.3 $-\sigma_{F}$ -o^{__} 0.2 0.1 **NEH** (meters) 0.0 -0.1 -0.2 Sdev mean -0.3 N: -0.0889 0.0941 E: 0.0751 0.0869 -0.4



495000

500000

505000

510000

490000

-0.5

-0.6

470000

475000

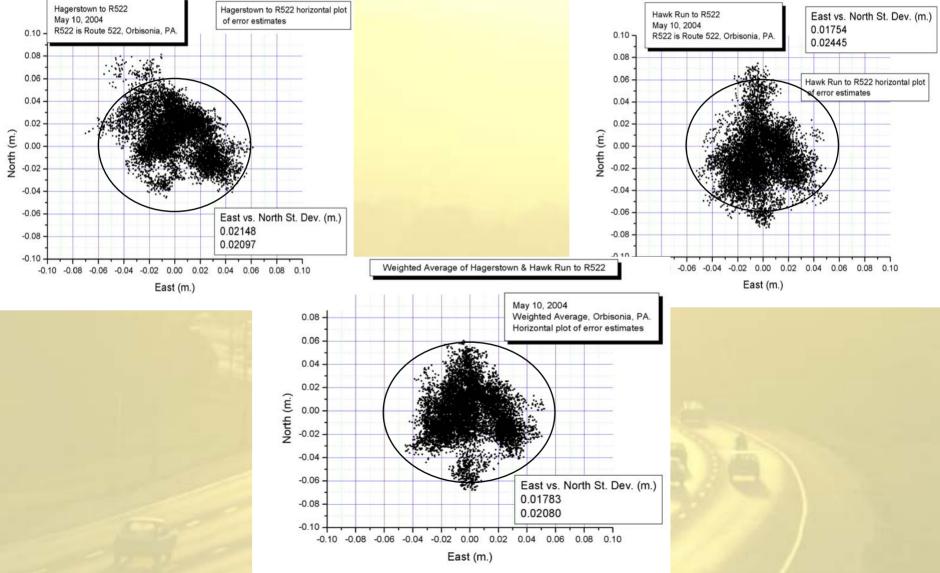
480000

485000

H: -0.0623 0.1392

Steady-state

Multi-Station - Phase II

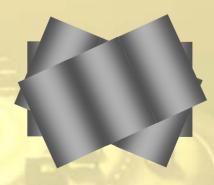


Documentation Package Phase III

- HA ECR Form;
- HA Prototype R&D Plan;
- HA Program Management Plan (PMP);
- HA User Objectives Definition Document;
- HA Equipment Integrated Logistics Support Plan (EILSP);
- System Operational Verification Test (SOVT) Plan;
- Test Procedure for Functional Tests;
- Test Procedure for Site Coverage Tests;
- Documentation Package for Hagerstown; Hawk Run; Topeka; St. Marys; Lincoln; and Pueblo.

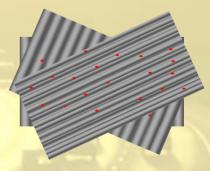
- What You Need:
 - Satellite Lock
 - Ground based system broadcasting observables
 - Multiple reference stations at less than 200 mile baselines
 - Accurate Ephemeris
 - Accurate Clock data
 - Good ionosphere model
 - Good Troposphere model
 - Integrity Check

- What You Get:
 - Initial .5 to 2 meter code accuracy
 - Reduced search space for integers
 - Very fast integer resolution at long ranges



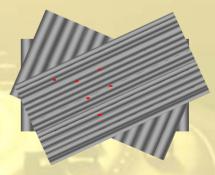
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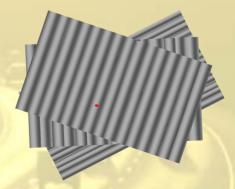
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Continuing Research

- Independent Ranging System
 - Small Business Innovative Research
 - Phase 1 complete
 - Paper Analysis How It Could Work
 - Beyond 100 Mile Range
 - » Multipath/Phase Shifts Degrades Solution
 - Other Signals of Opportunity
 - » Improves Performance
 - Phase II starting shortly
 - Product Development

Summary

- HA-NDGPS signal successfully broadcast from multiple locations
 - State-of-the-Art modulation
 - Reliable diplexing technology
- Developed new atmospheric modeling approaches
- Accuracy better than 10 cm horizontally, 95%
- Availability above 99.9%
- Implementation cost <\$100,000 per site
- Potential:
 - stand alone navigation service
 - High Accuracy in Short Time

Contact Information

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Phase I Test Report <u>http://www.tfhrc.gov/its/ndgps/02110/index.htm</u> Phase II Test Report <u>http://www.tfhrc.gov/its/pubs/05034/index.htm</u>